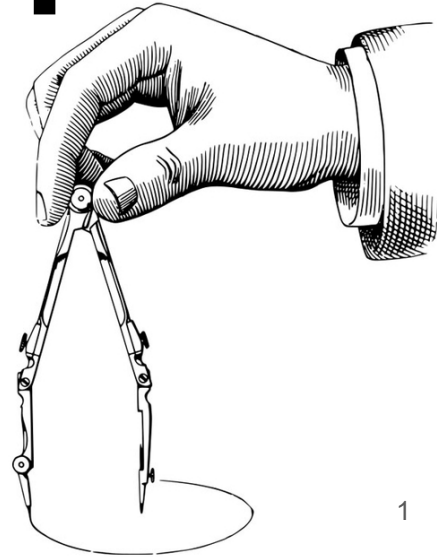




Charting The Cyber- Physical System Security Landscape

Miguel A. Arroyo

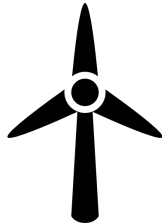
Ph.D. Candidacy Exam
Nov. 27th, 2018





Cyber-Physical Systems

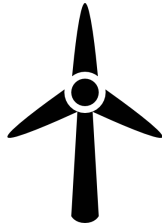
*Systems that sense and actuate on
the physical environment.*





Cyber-Physical Systems

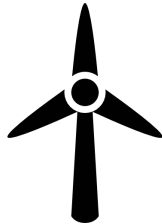
*Systems that **sense** and actuate on the physical environment.*





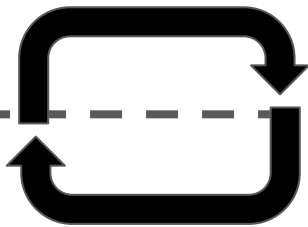
Cyber-Physical Systems

*Systems that **sense** and **actuate** on
the physical environment.*

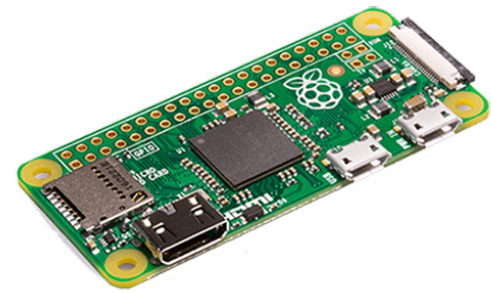
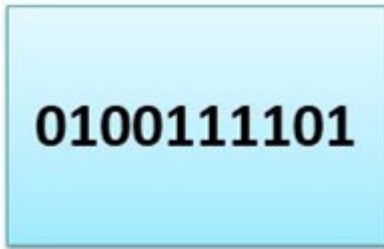




Analog



Digital

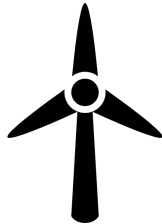




The Problem

“Our daily lives will depend more and more on these systems. Our lives, our money, our welfare. How can we design cyber-physical systems that we can bet our lives on?”

--Jeannette M. Wing

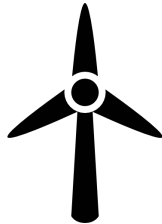




The Problem

*“Our daily lives will depend more and more on these systems. Our lives, our money, our welfare. **How can we design cyber-physical systems that we can bet our lives on?**”*

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Safety





Security



Safety

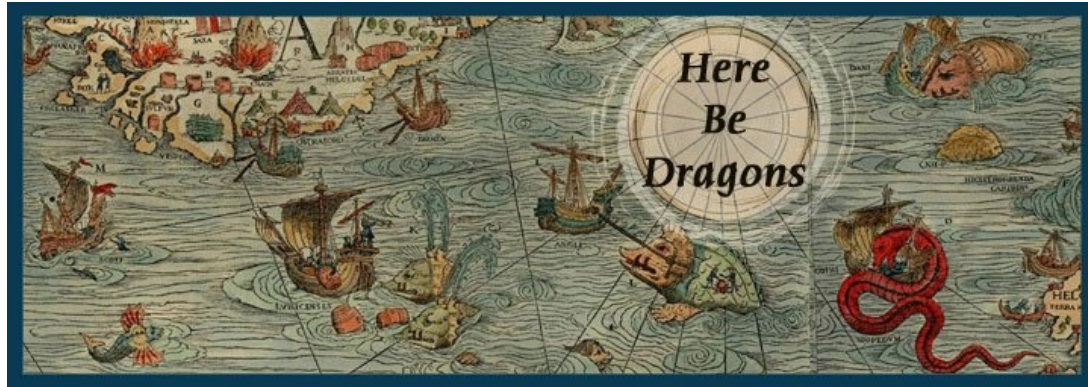




The Claim

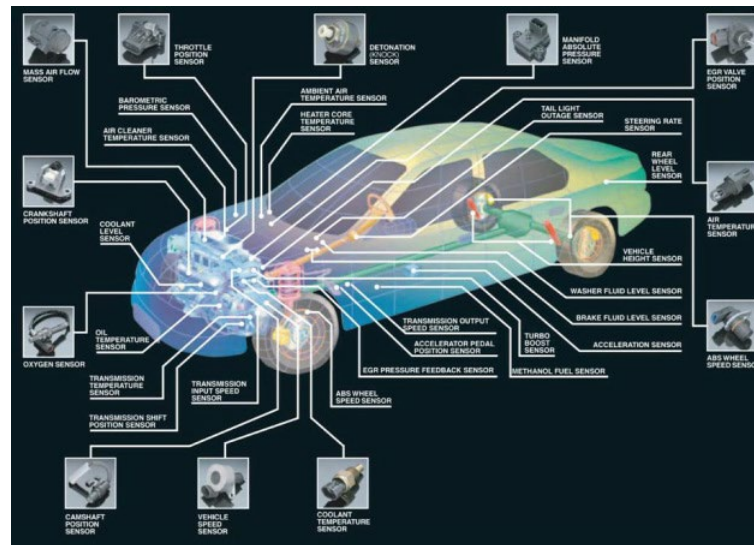
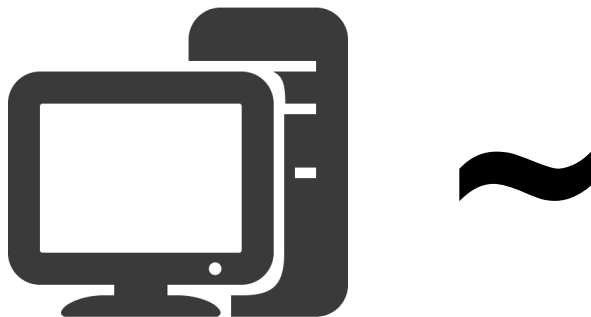


CPS Security is Different



CPS Security is Different...

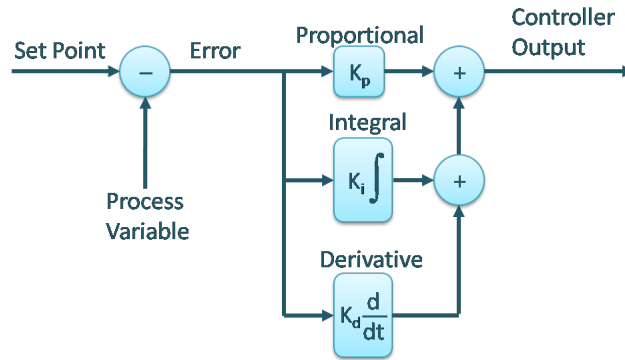
- It can overlap with traditional cyber-security.
 - Similar software and network vulnerabilities [1,4].





CPS Security is Different...

- It opens up unexplored surfaces.
 - Control algorithms [2,3]
 - Physical environment [5-10]





Research Question



1968



2018

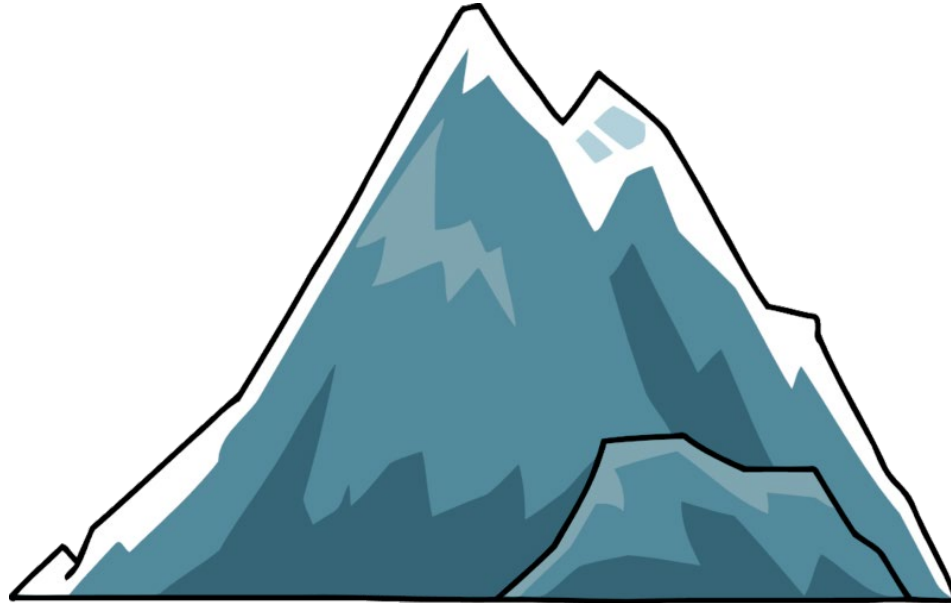


Research Question

To what degree can existing security techniques help and what new opportunities exist?



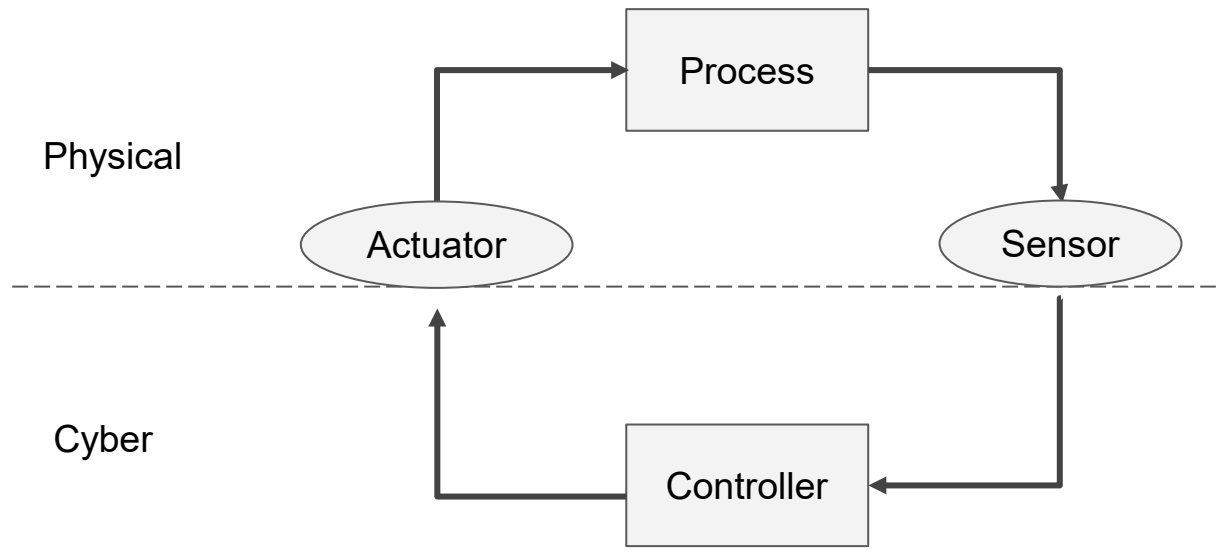
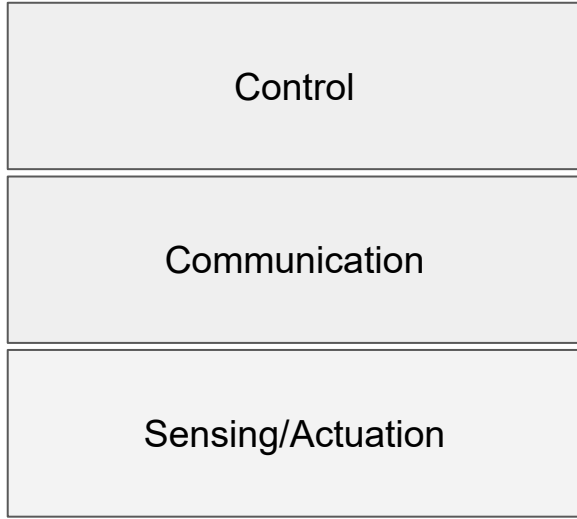
CPS Fundamentals



A 30,000ft view

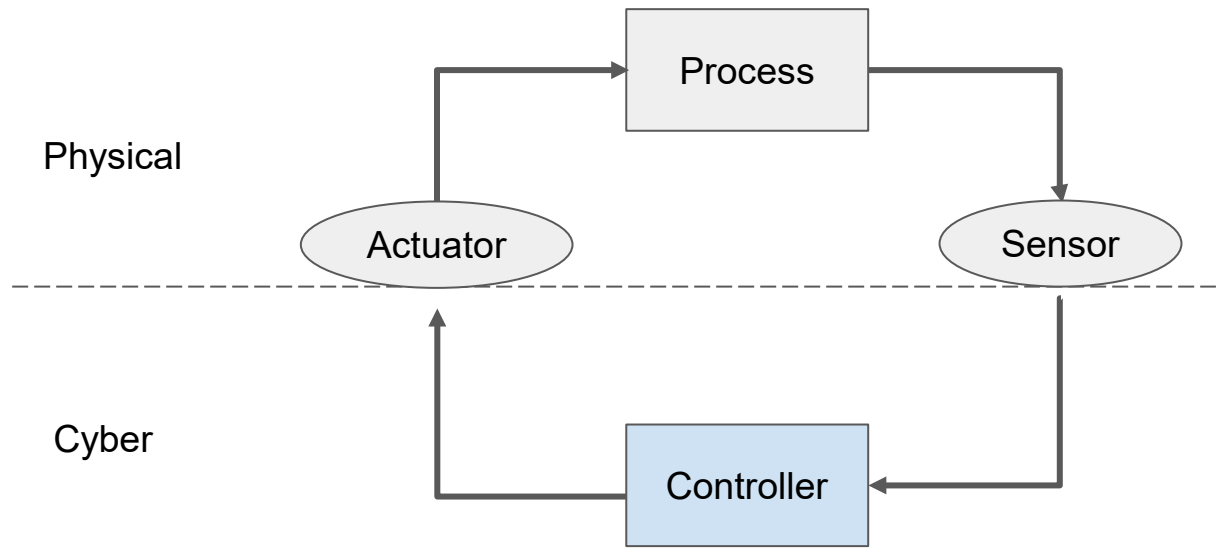
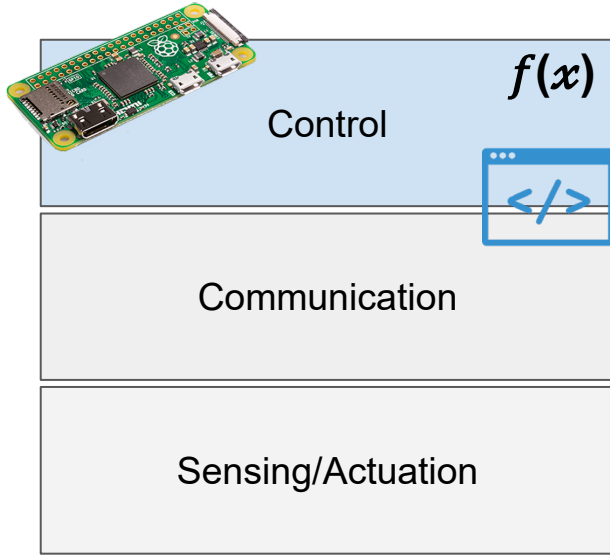


CPS Components



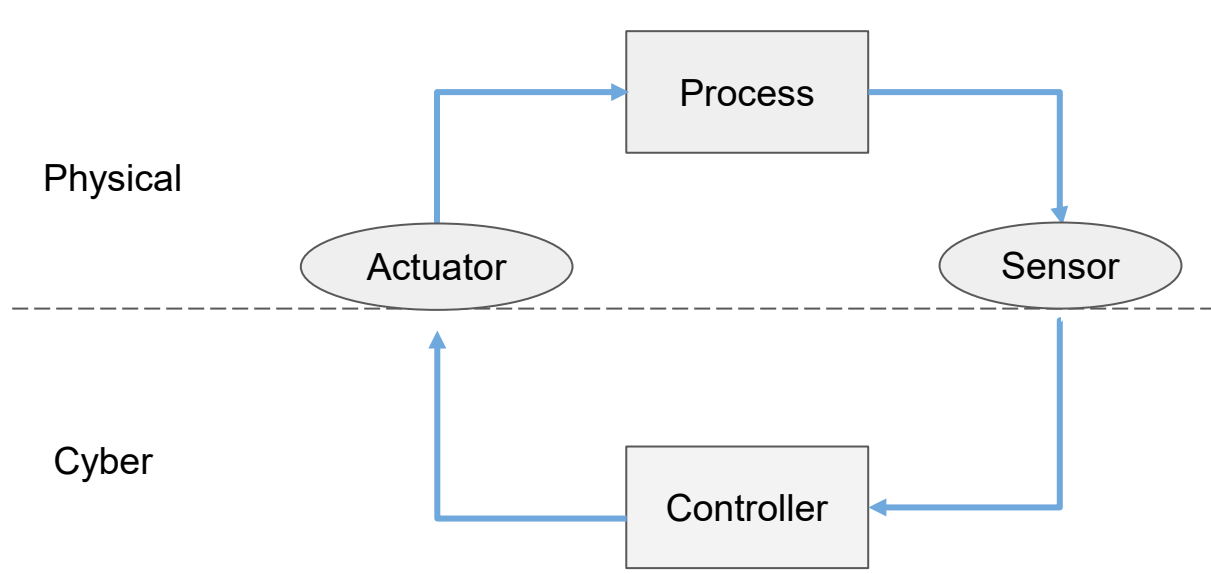
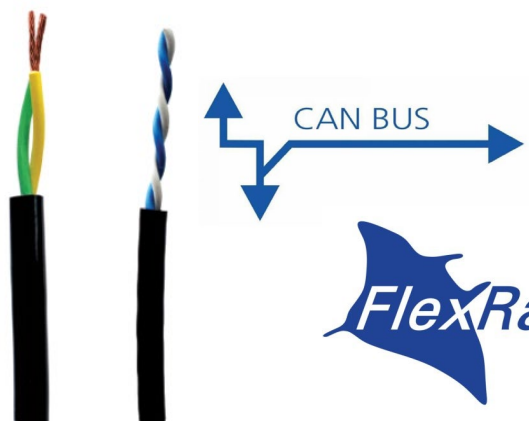
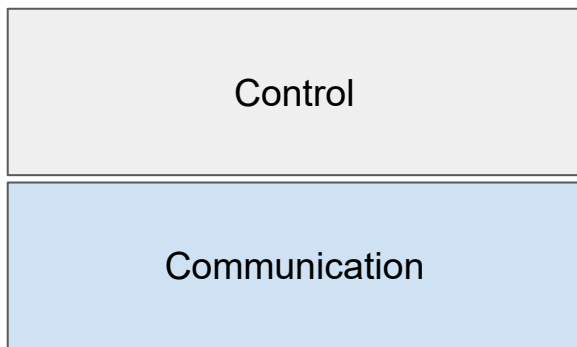


CPS Components



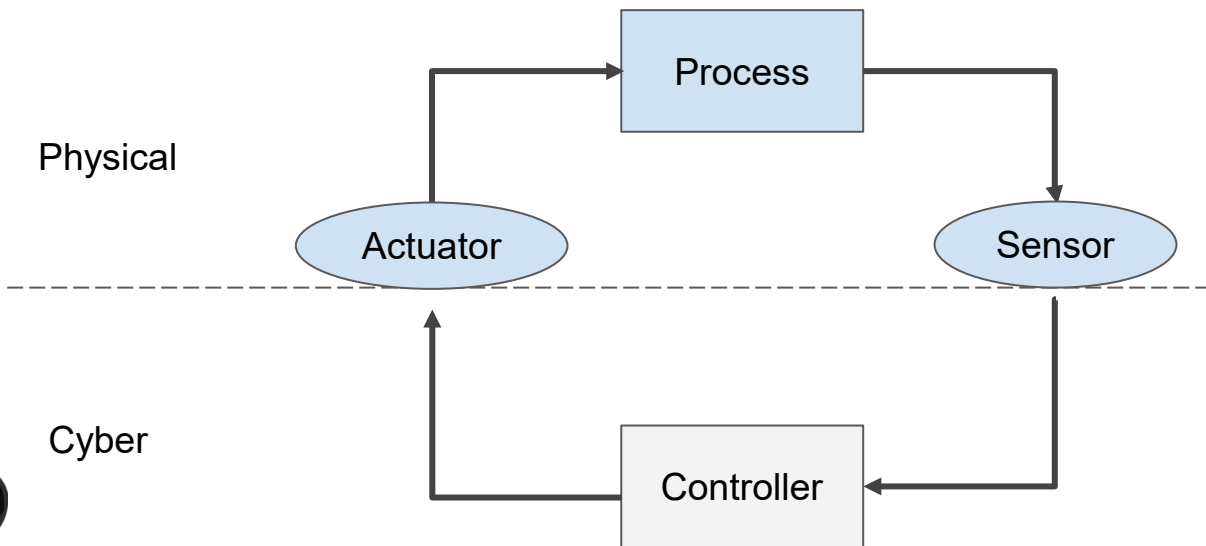
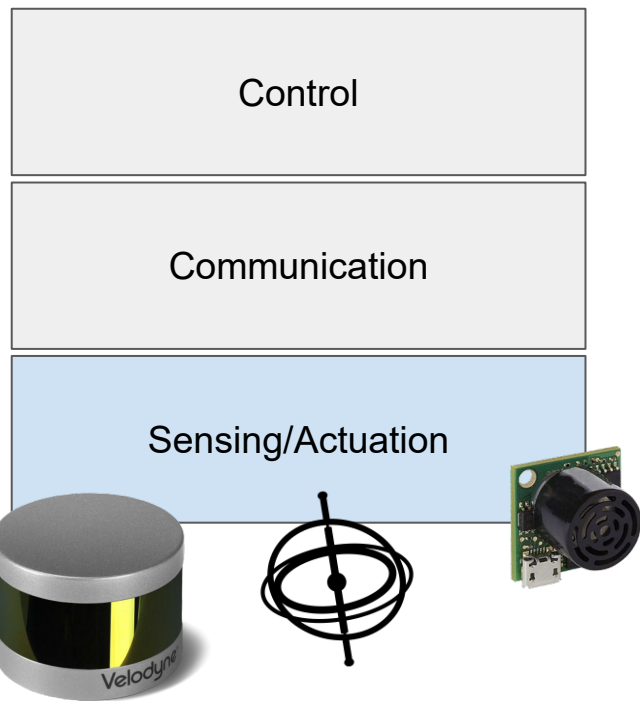


CPS Components



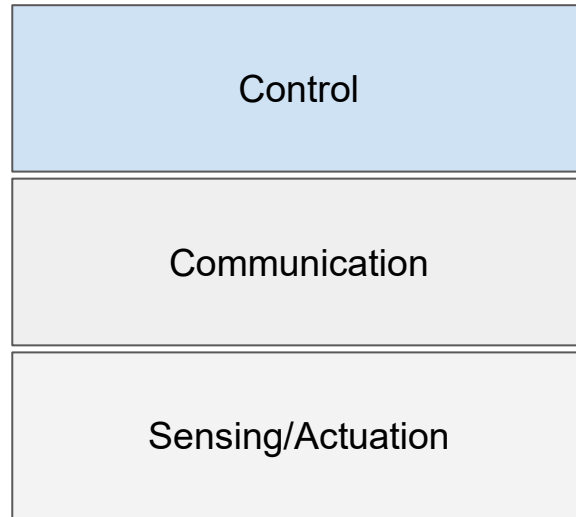


CPS Components





Threat Vectors





Threat Vectors: **Control**

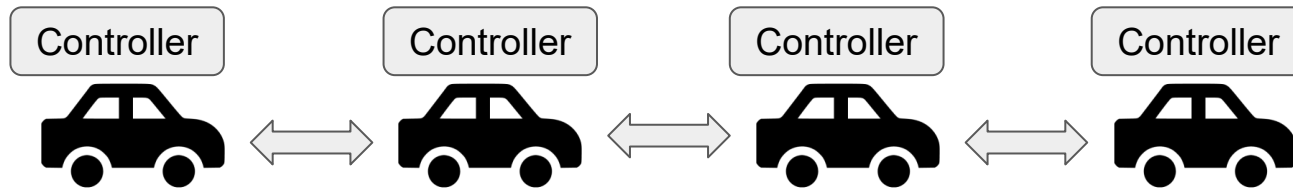
- **Algorithmic**
 - Violation of assumptions in control algorithms due to adversarial behavior.



Threat Vectors: **Control**

- **Algorithmic**

- Violation of assumptions in control algorithms due to adversarial behavior.

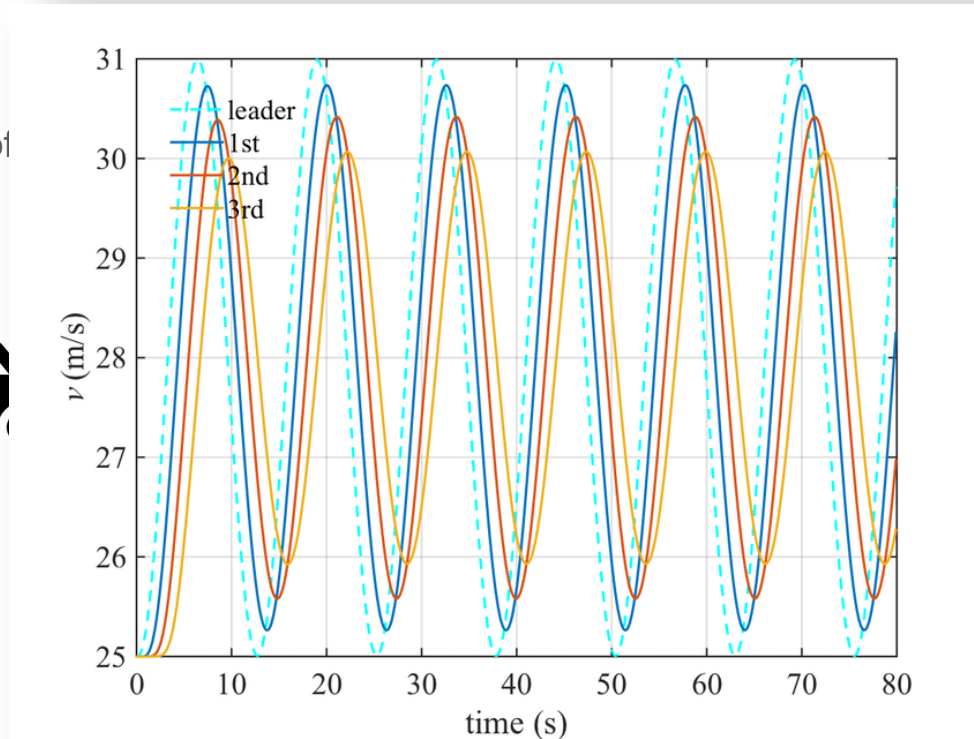




Threat Vectors: **Control**

- **Algorithmic**

- Violation of



ior.



Threat Vectors: **Control**

- **Algorithmic**

- Violation of assumptions in control algorithms due to adversarial behavior.

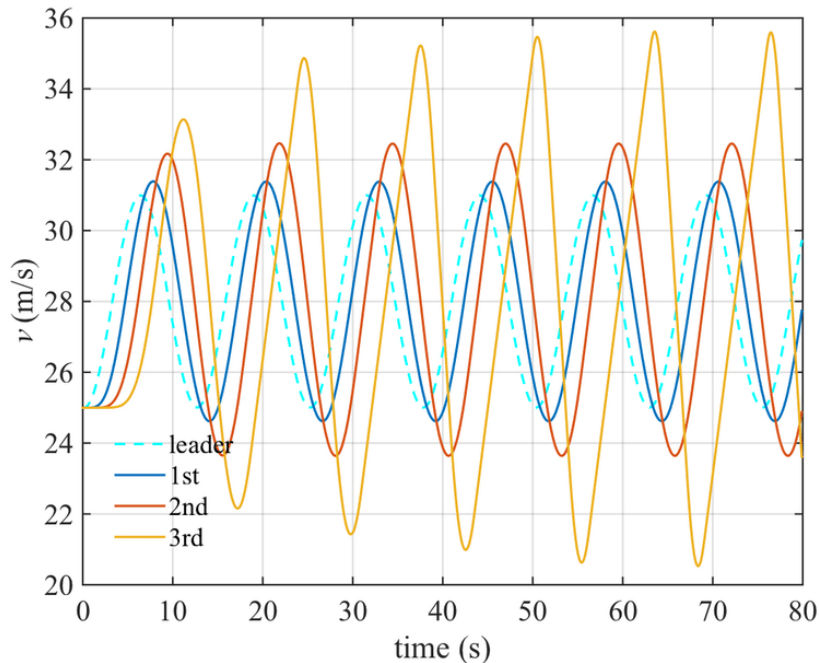
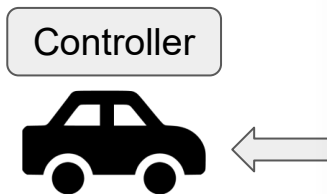


Destabilize a platoon of vehicles using Adaptive Cruise Control.

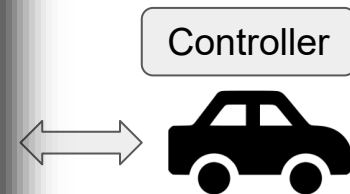


Threat Vectors: **Control**

- **Algorithmic**
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behavior.



Destabilize a platoon of vehicles using Adaptive Cruise Control.



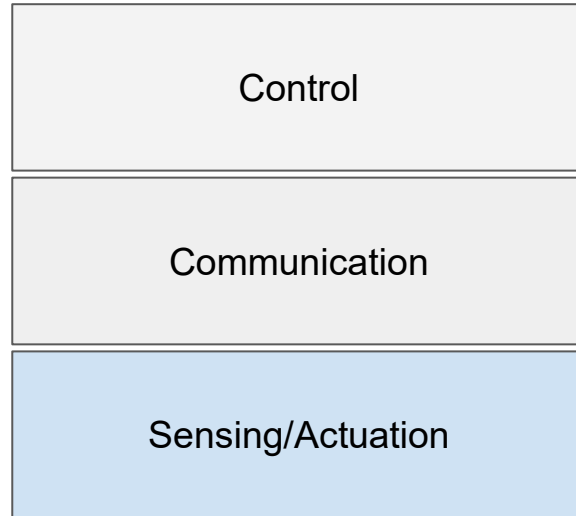
Threat Vectors: **Control**

- **Algorithmic**

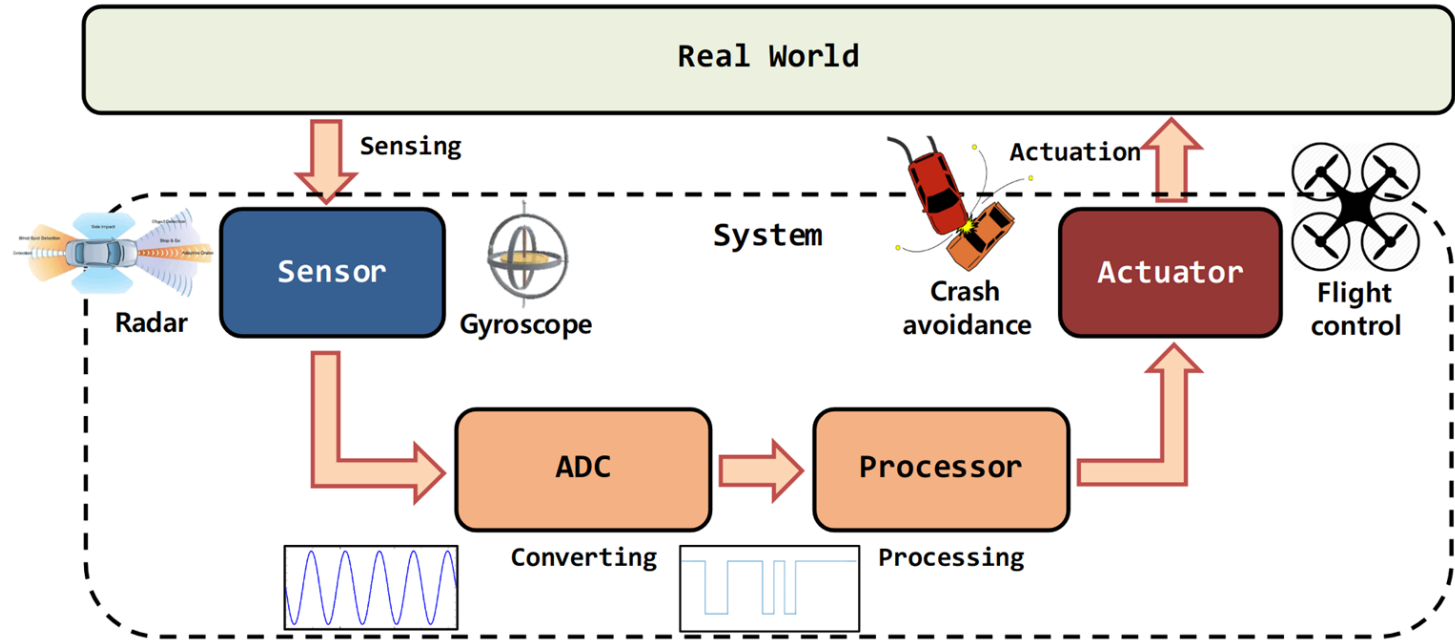
- Violation of assumptions in control algorithms due to adversarial behavior.

Take Away

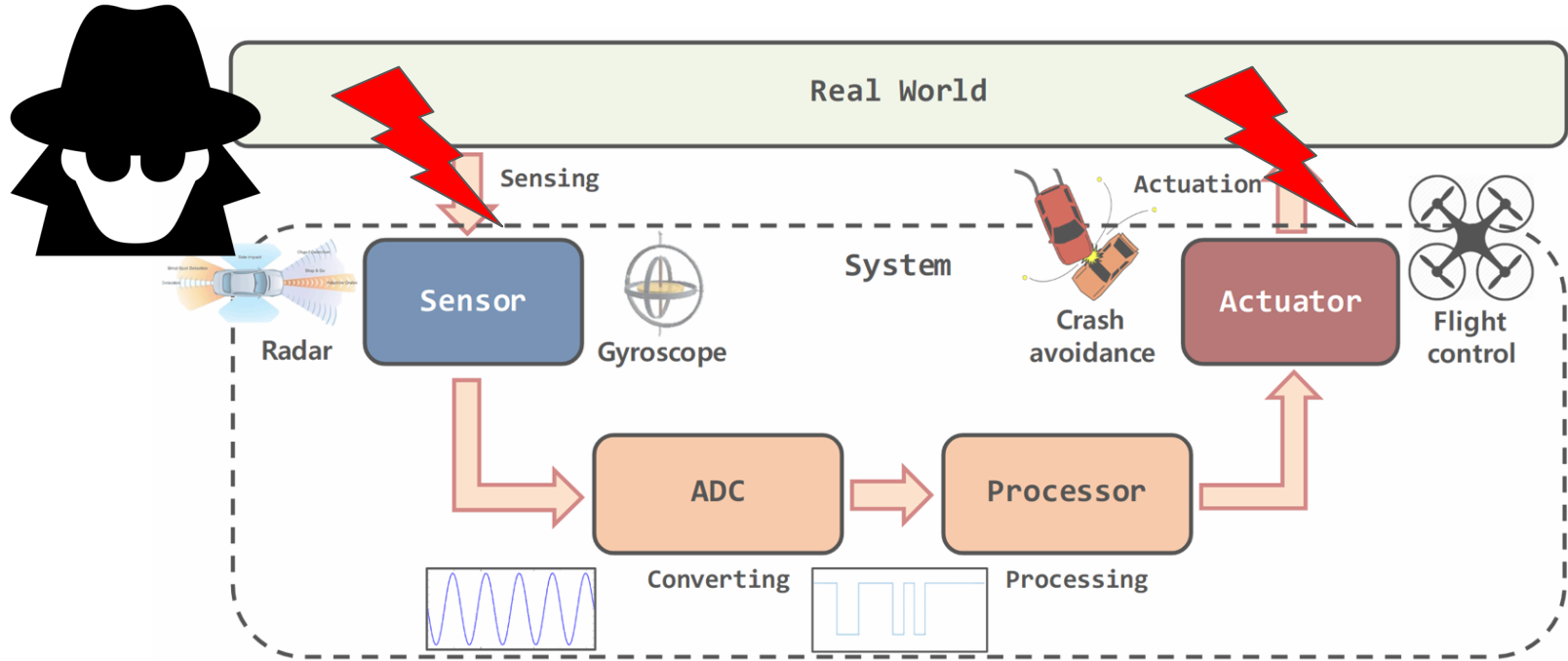
Even perfectly secure hardware & software may be compromised if control algorithms cannot properly handle malicious inputs.



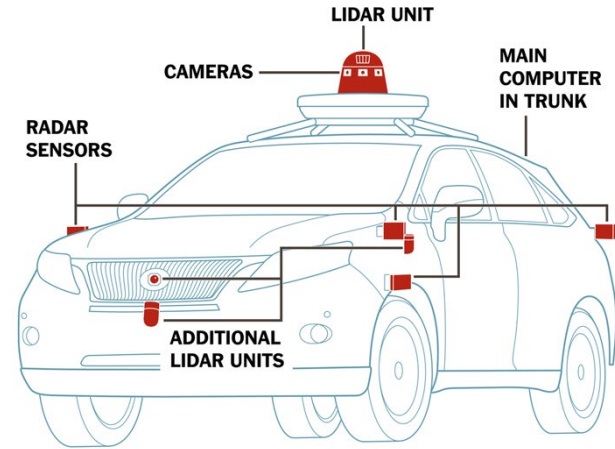
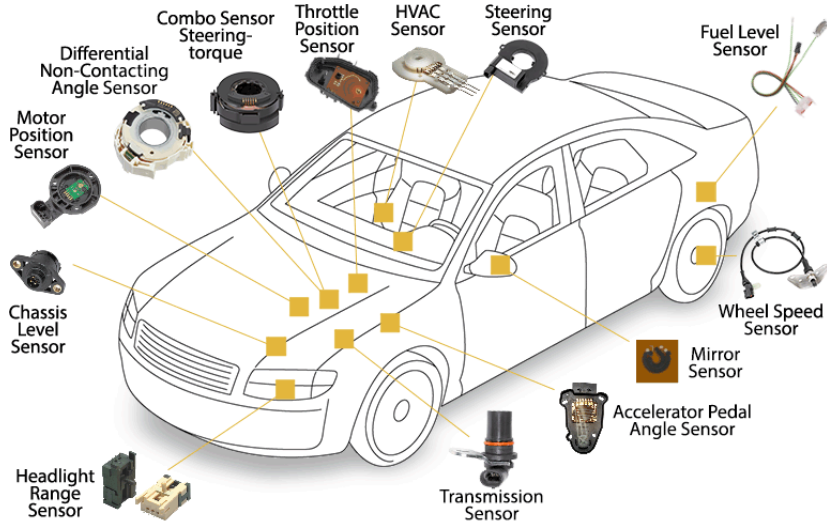
Threat Vectors: **Sensing & Actuation**



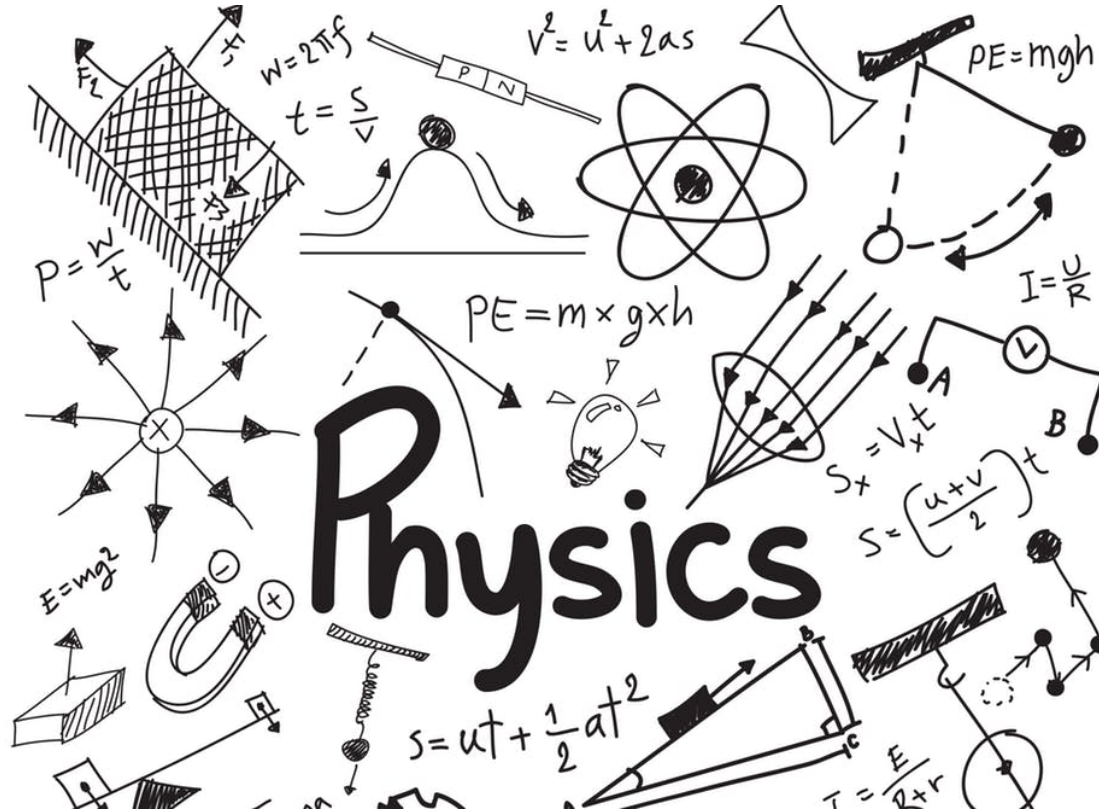
Threat Vectors: Sensing & Actuation



Threat Vectors: Sensing & Actuation

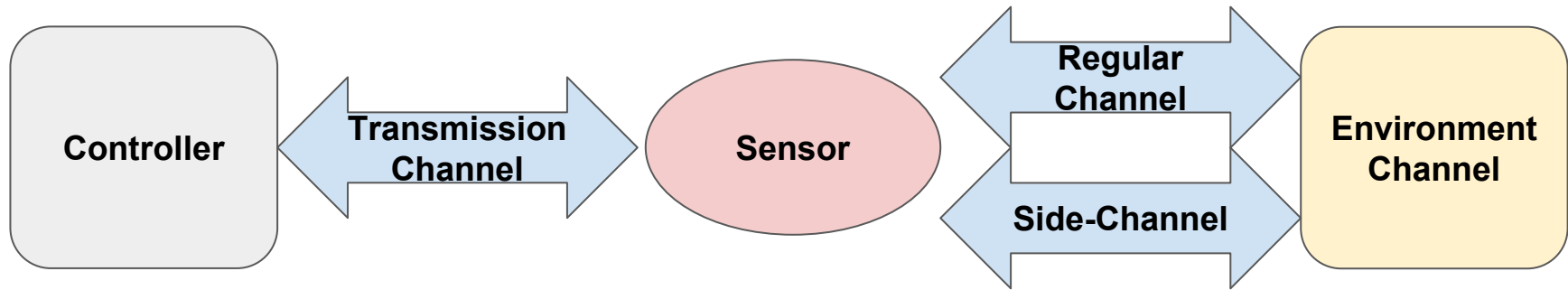


Threat Vectors: Sensing & Actuation



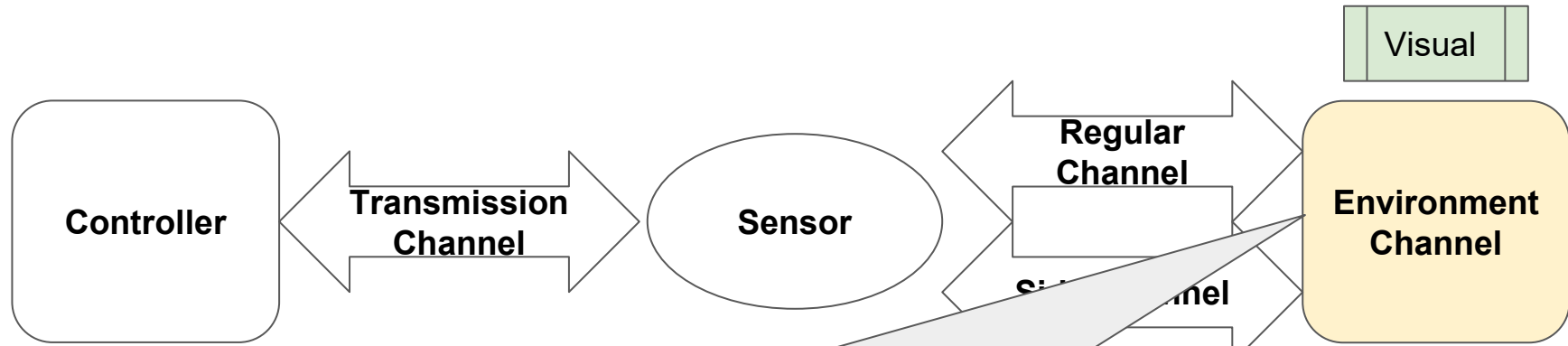


Threat Vectors: **Sensing & Actuation**





Threat Vectors: **Sensing & Actuation**



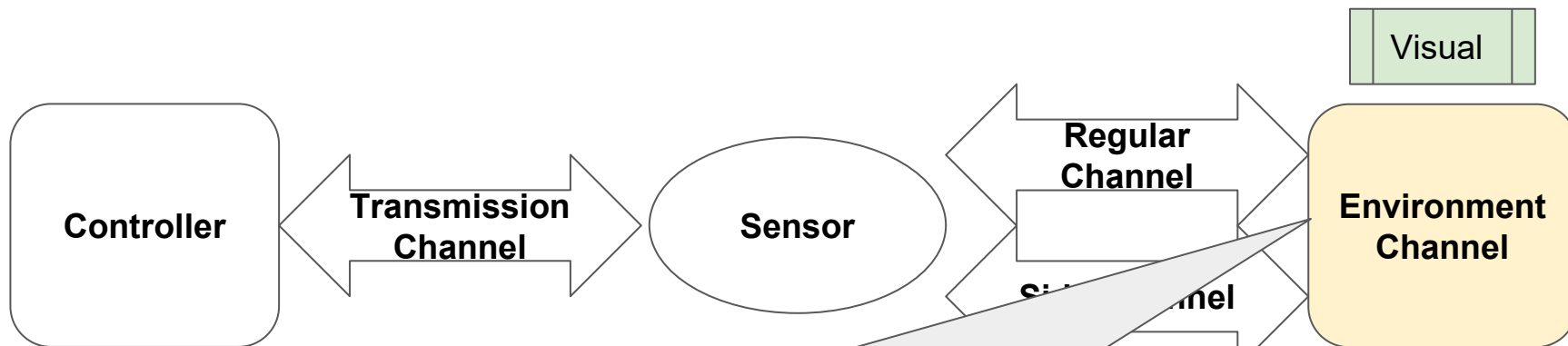
Environment Channel: Surrounding where sensing occurs.

Davidson et al. [9] - Project visual pattern to exploit optical flow sensors.

Eykholt et al. [10] - Minimally modify visual environment to force DNN misclassification.



Threat Vectors: **Sensing & Actuation**



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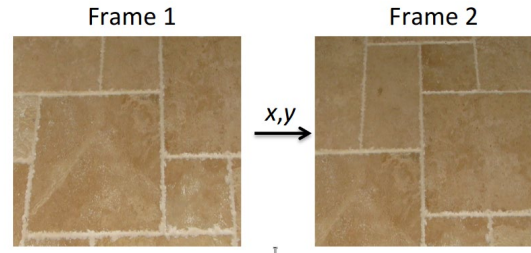
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Threat Vectors: **Sensing & Actuation**

- **Visual Spoofing**

- Modification of the visual environment.

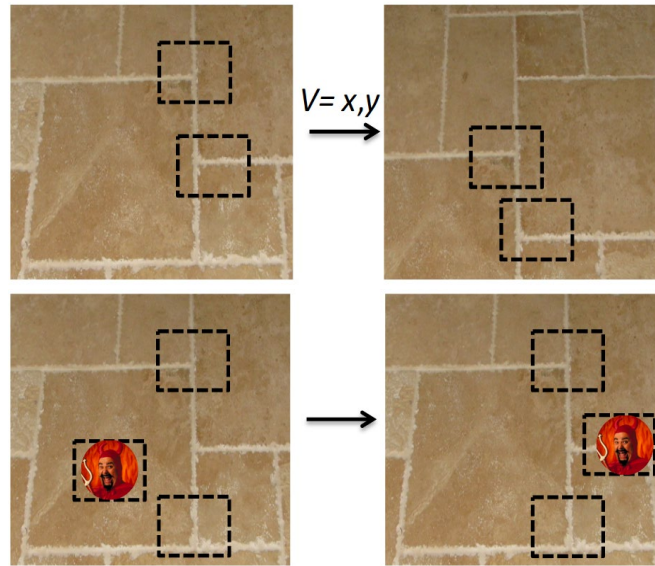




Threat Vectors: **Sensing & Actuation**

- **Visual Spoofing**

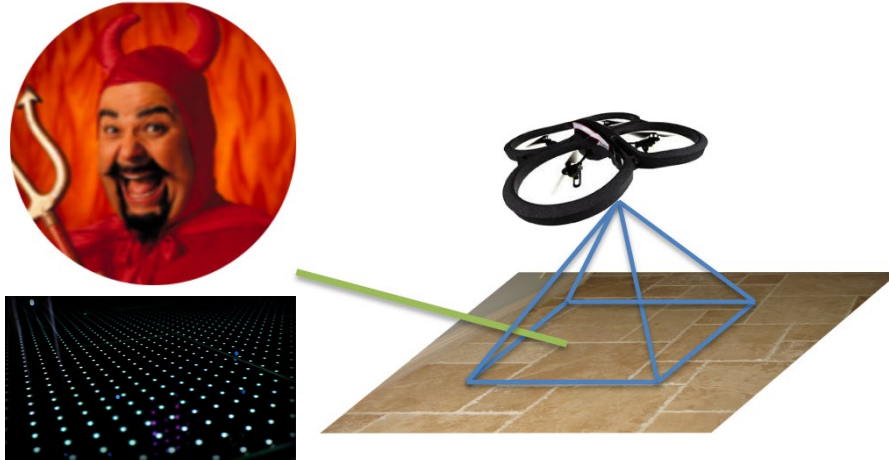
- Modification of the visual environment.





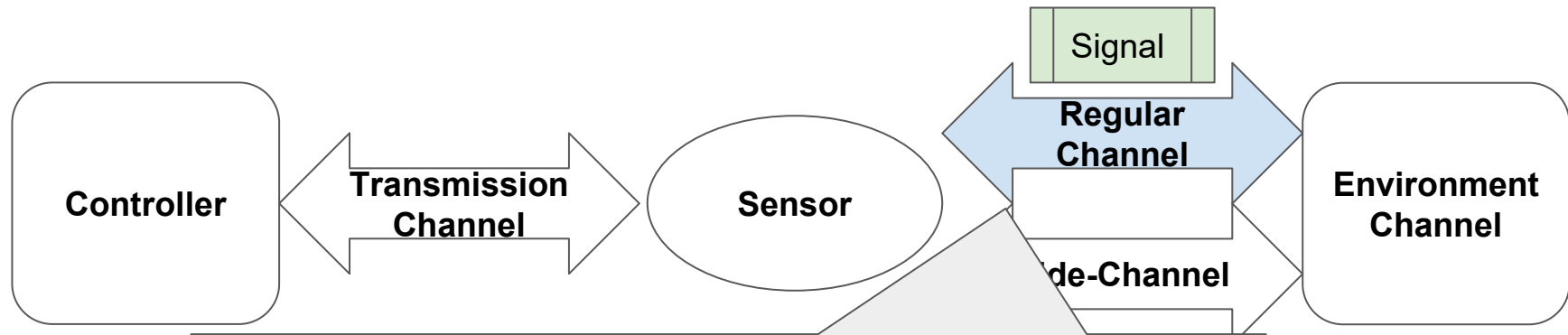
Threat Vectors: **Sensing & Actuation**

- **Visual Spoofing**
 - Modification of the visual environment.





Threat Vectors: **Sensing & Actuation**



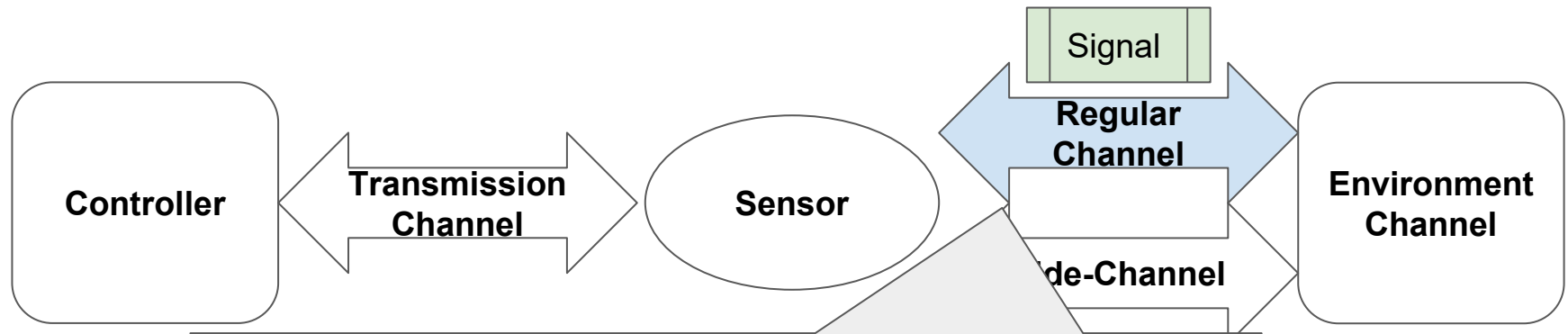
Regular Channel: Physical quantity being directly sensed.

Shoukry et al. [5] - Manipulate magnetic vehicle braking sensor.

Park et al. [8] - Saturate readings of infusion pump IR sensor.



Threat Vectors: **Sensing & Actuation**



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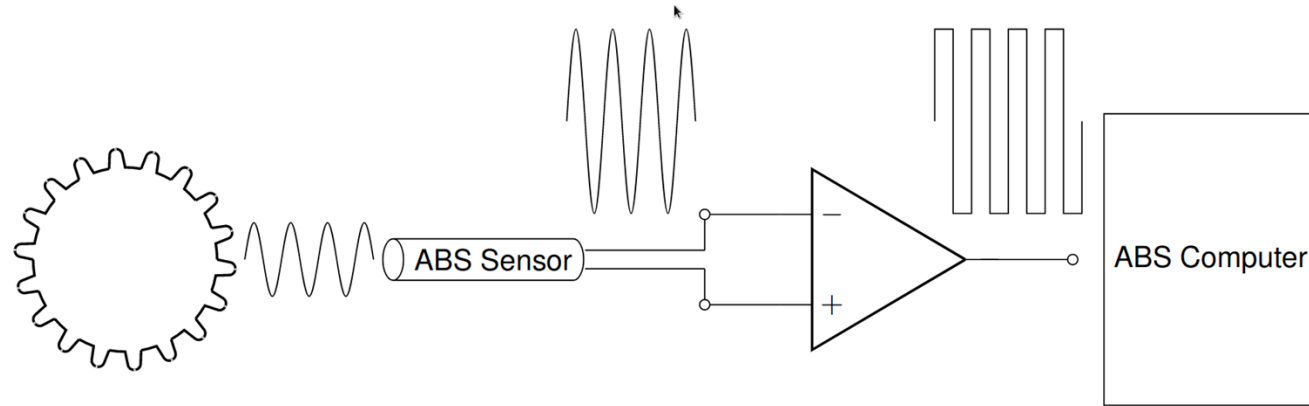
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Threat Vectors: **Sensing & Actuation**

- **Signal Spoofing**

- Modification of the analog signal being sensed.





Threat Vectors: **Sensing & Actuation**

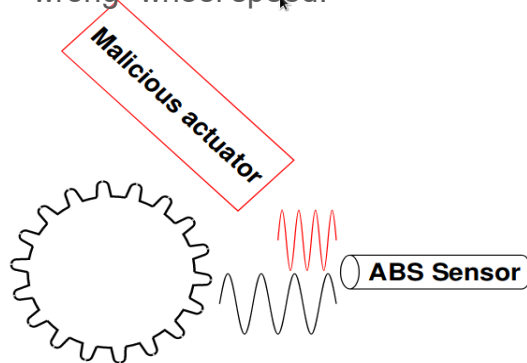
- **Signal Spoofing**

- Modification of the analog signal being sensed.

Disruptive attack:

Magnetic field is superimposed to the original magnetic field.

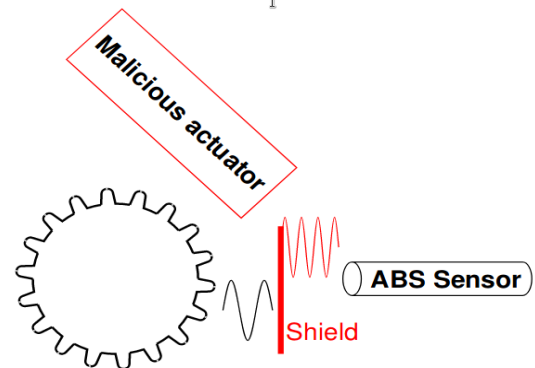
Result: sensor will measure “wrong” wheel speed.



Spoofing attack:

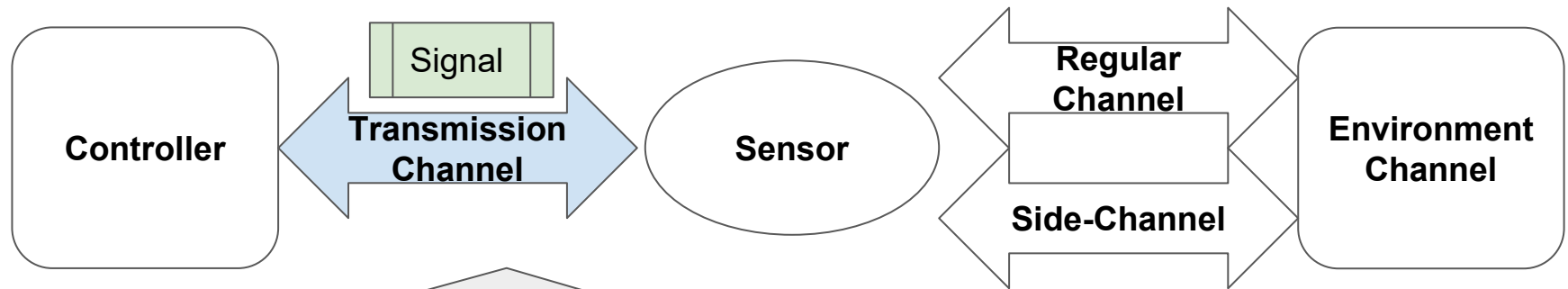
Attacker shields the sensor from the environment while generating synthetic signal.

Result: precisely control the “measured” wheel speed.





Threat Vectors: **Sensing & Actuation**

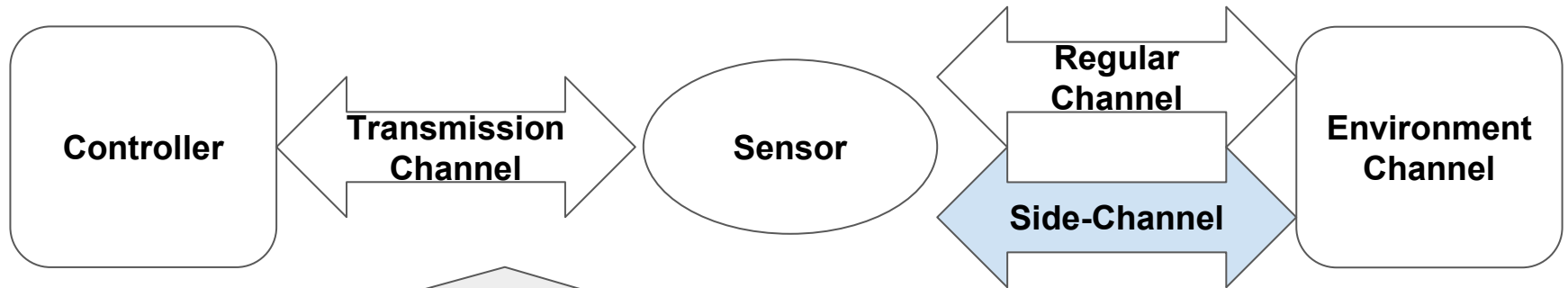


Transmission Channel: Interconnect between sensor and digitalization components.

Kune et al. [6] - Inject EMI to transmission wire in cardiac devices.



Threat Vectors: **Sensing & Actuation**

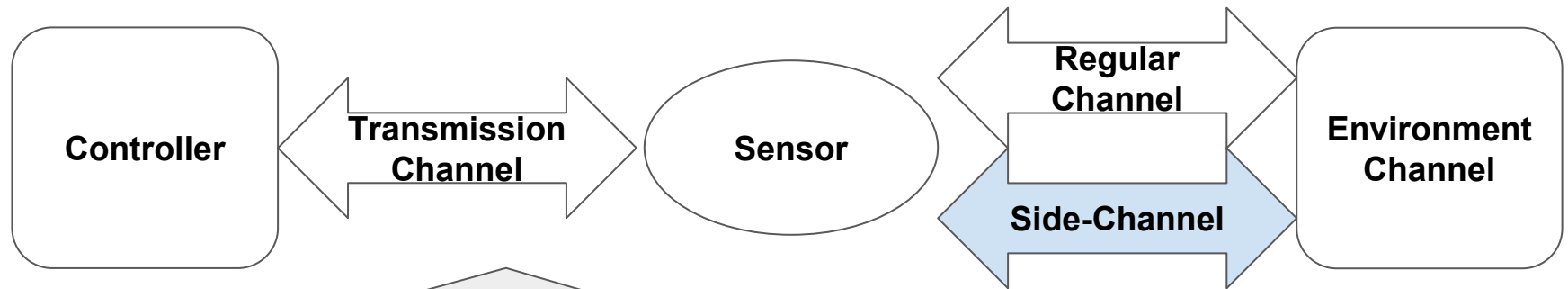


Side-Channel: Physical quantity NOT being directly sensed.

Son et al. [7] - Force resonance behavior on MEMS gyroscope.



Threat Vectors: **Sensing & Actuation**



Side-Channel: Physical quantity NOT being directly sensed.

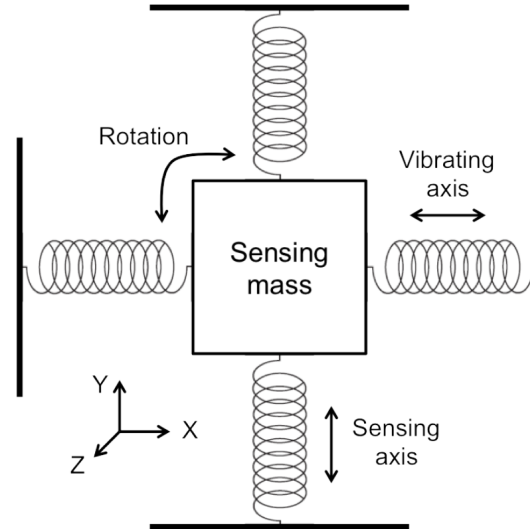
Son et al. [7] - Force resonance behavior on MEMS gyroscope.



Threat Vectors: **Sensing & Actuation**

- **Signal Spoofing**

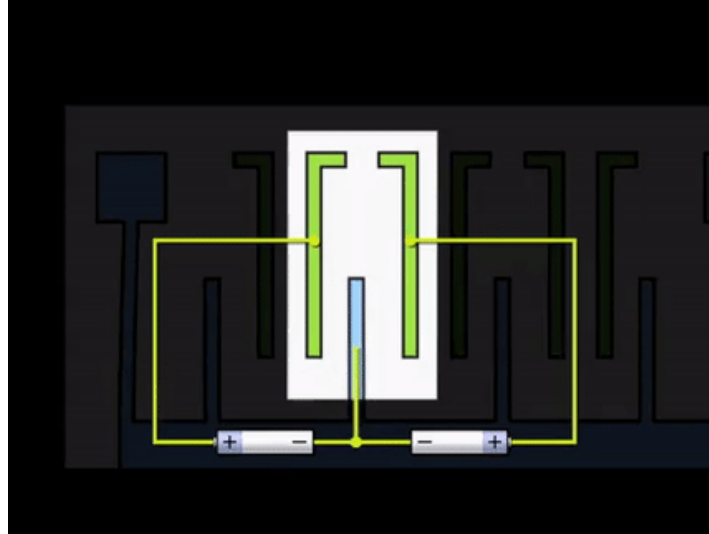
- Modification of the analog signal being sensed.





Threat Vectors: **Sensing & Actuation**

- **Signal Spoofing**
 - Modification of the analog signal being sensed.





Threat Vectors: **Sensing & Actuation**

- **Signal Spoofing**

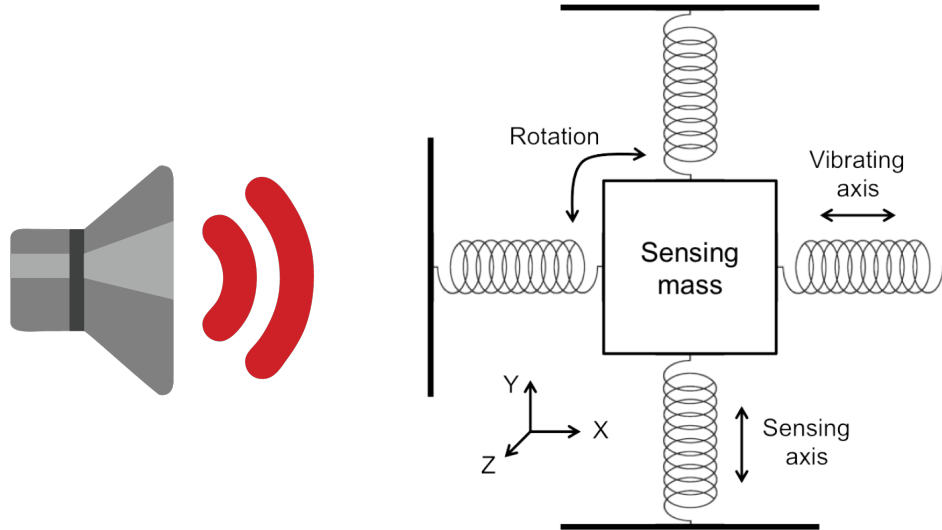




Threat Vectors: **Sensing & Actuation**

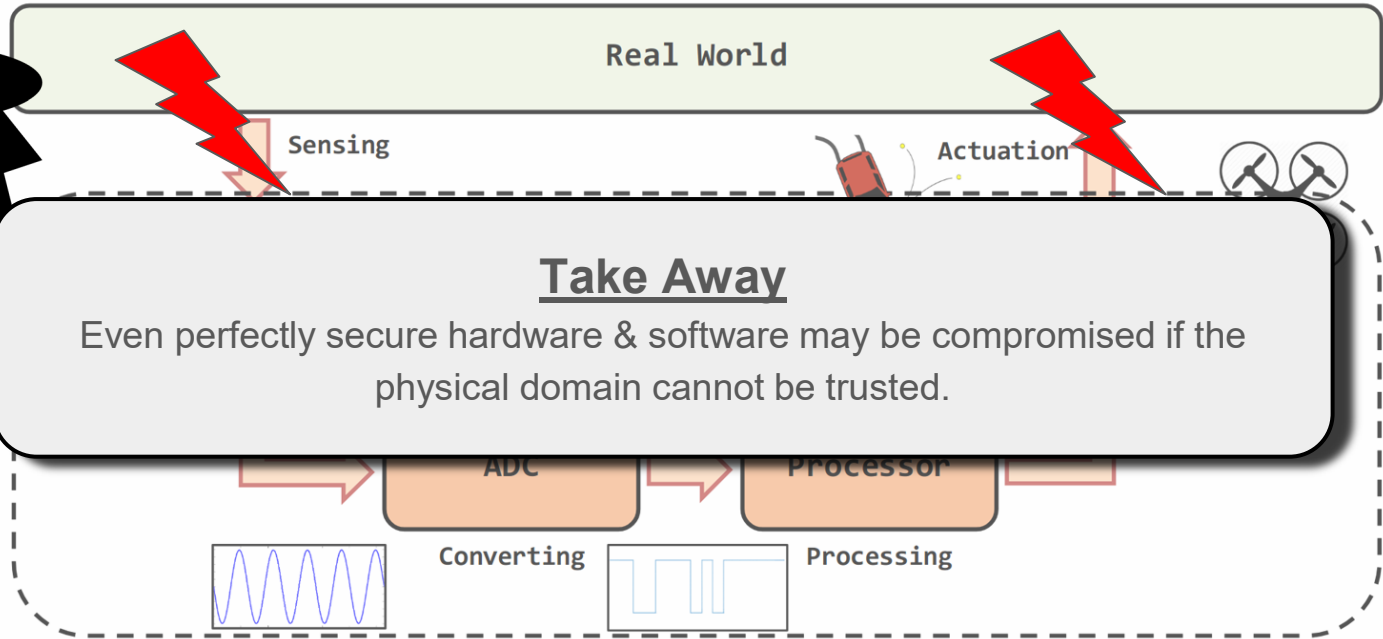
- **Signal Spoofing**

- Modification of the analog signal being sensed.



Use sound to cause MEMS sensors to resonate and destabilize drone.

Threat Vectors: **Sensing & Actuation**





CPS Fundamentals

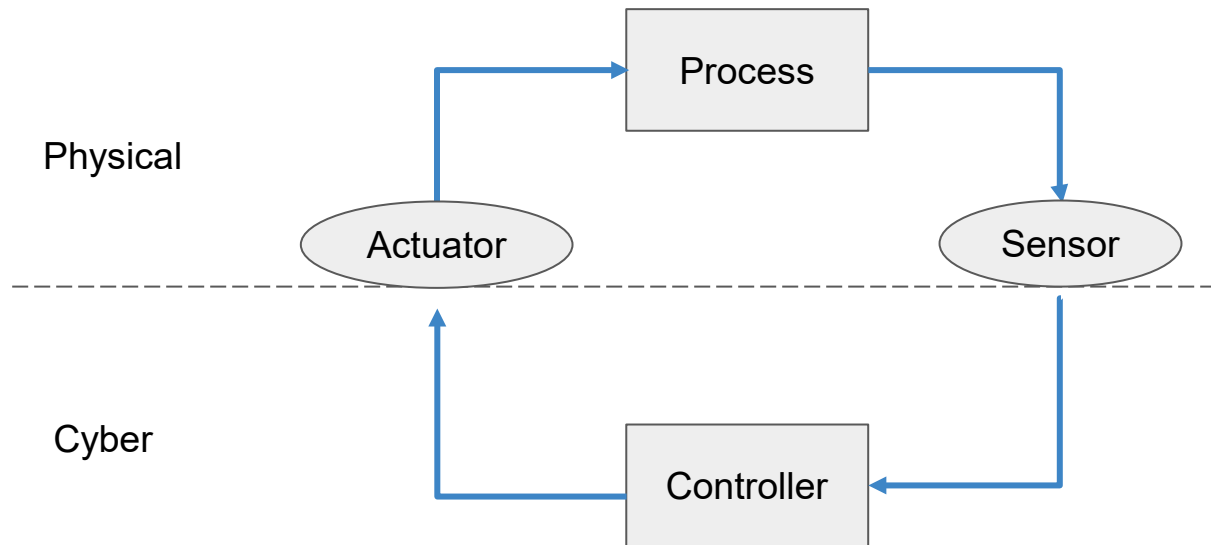


A 30,000ft view



CPS Properties

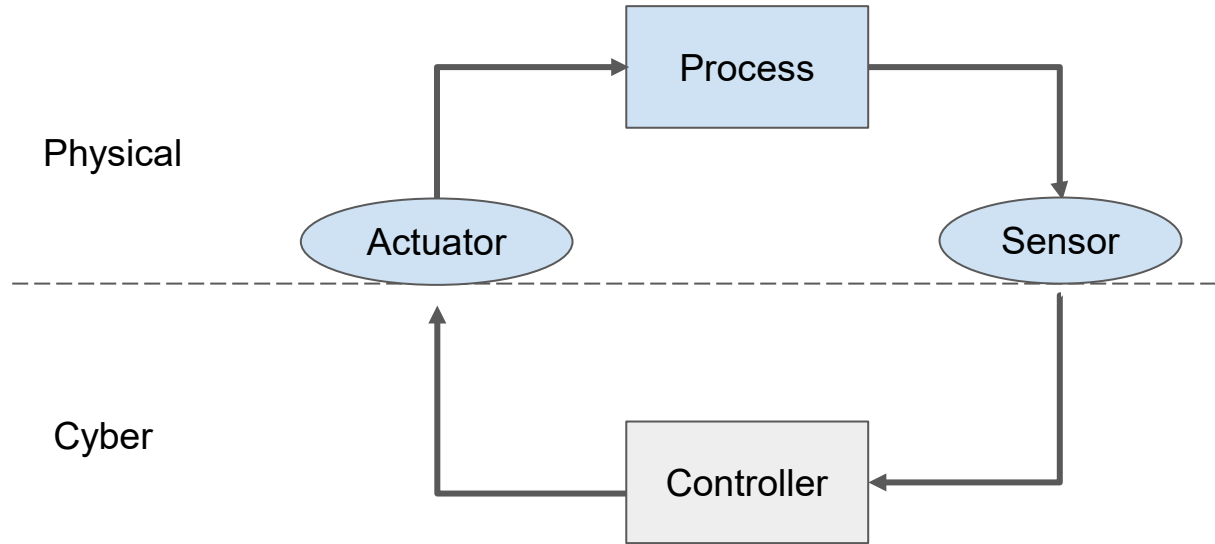
- Feedback





CPS Properties

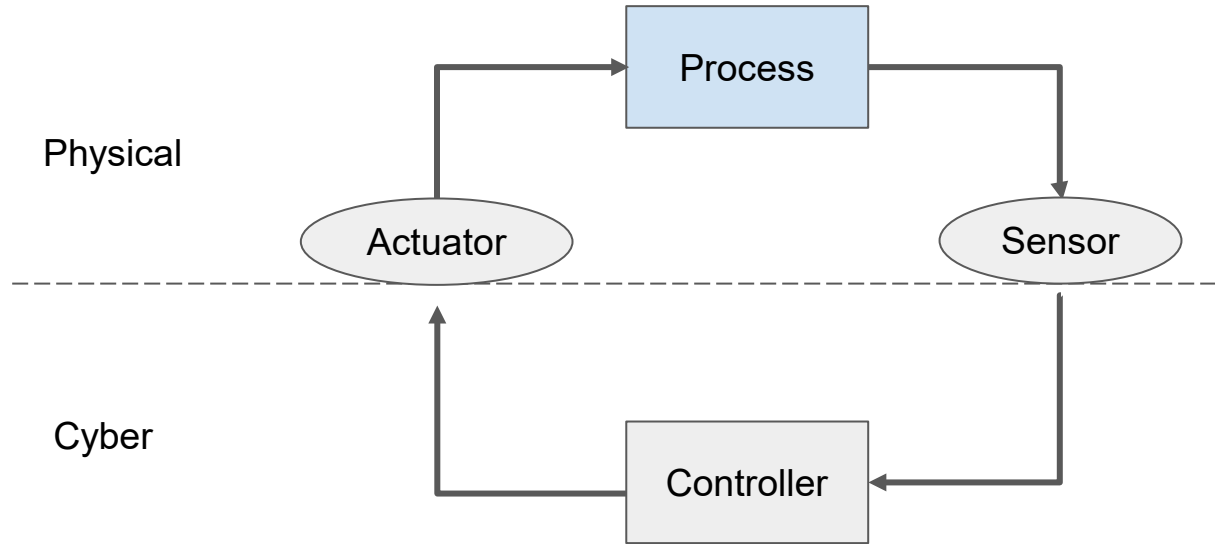
- Feedback
- **Dynamic**





CPS Properties

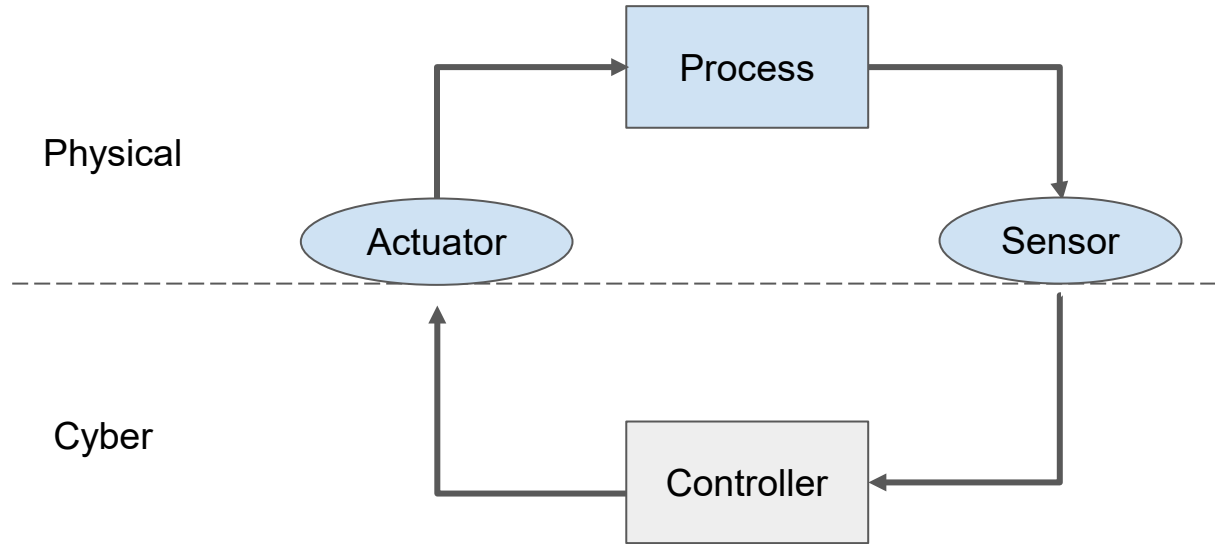
- Feedback
- Dynamic
- **Observable**





CPS Properties

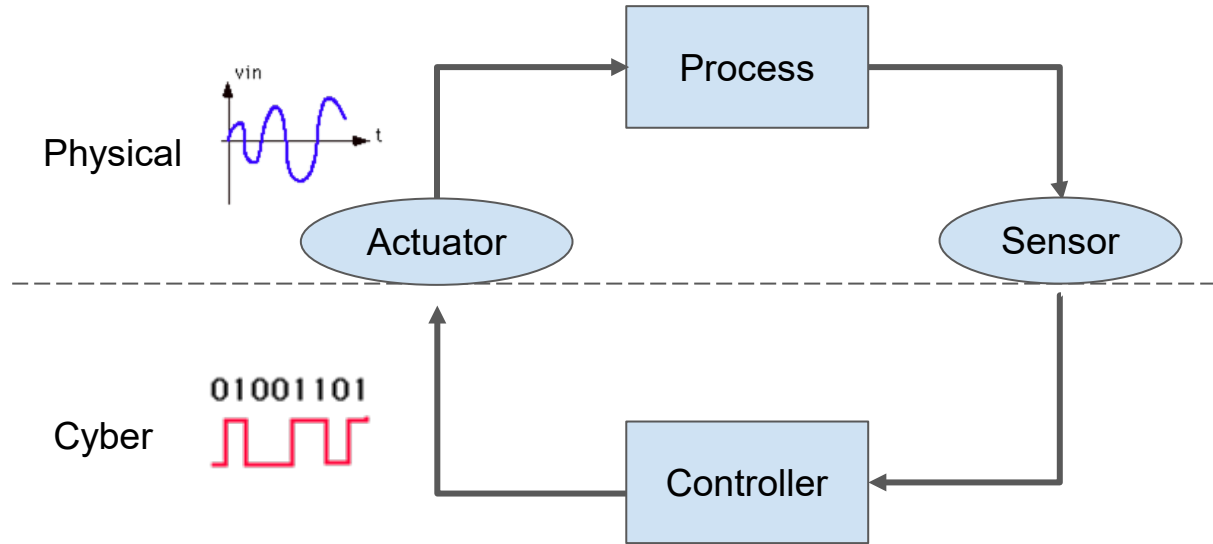
- Feedback
- Dynamic
- Observable
- **Physically Bounded**





CPS Properties

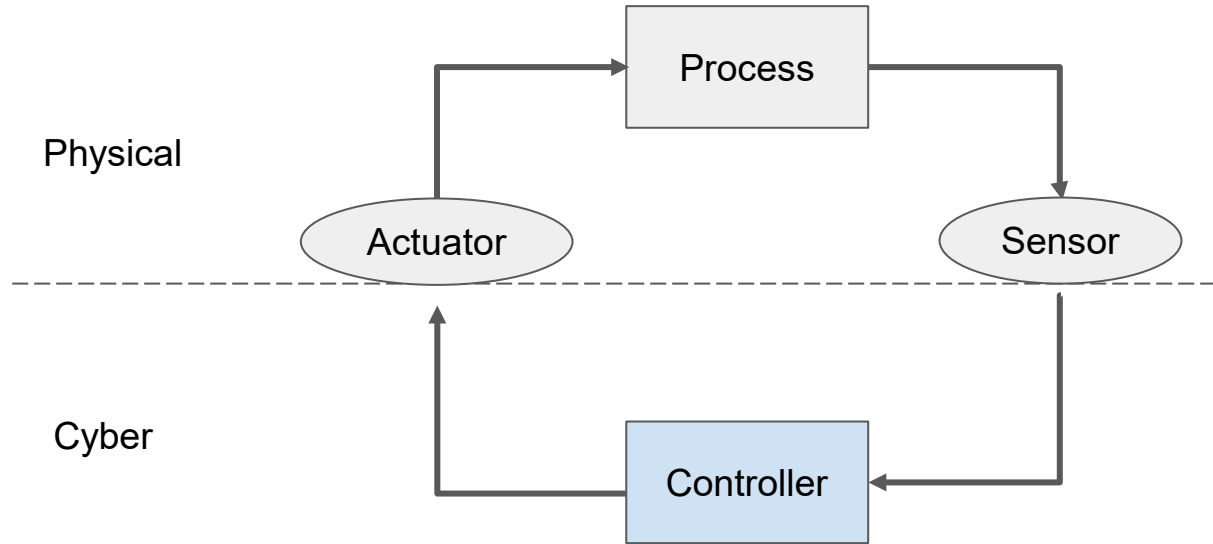
- Feedback
- Dynamic
- Observable
- Physically Bounded
- **Error Tolerant**





CPS Properties

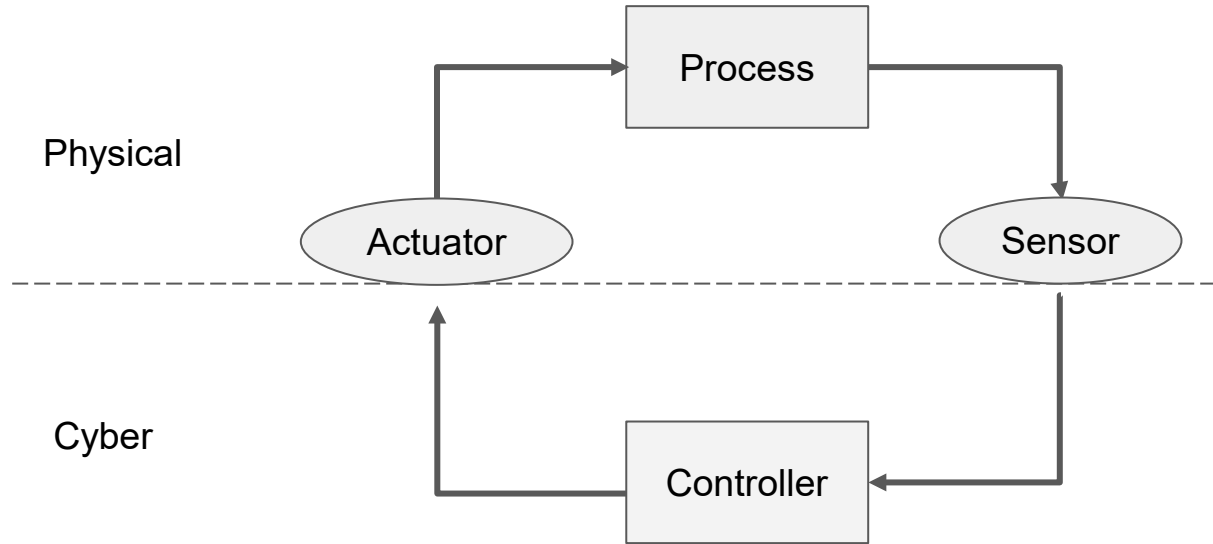
- Feedback
- Dynamic
- Observable
- Physically Bounded
- Error Tolerant
- **Event-driven**





CPS Properties

- Feedback
- Dynamic
- Observable
- Physically Bounded
- Error Tolerant
- Event-driven





CPS Properties

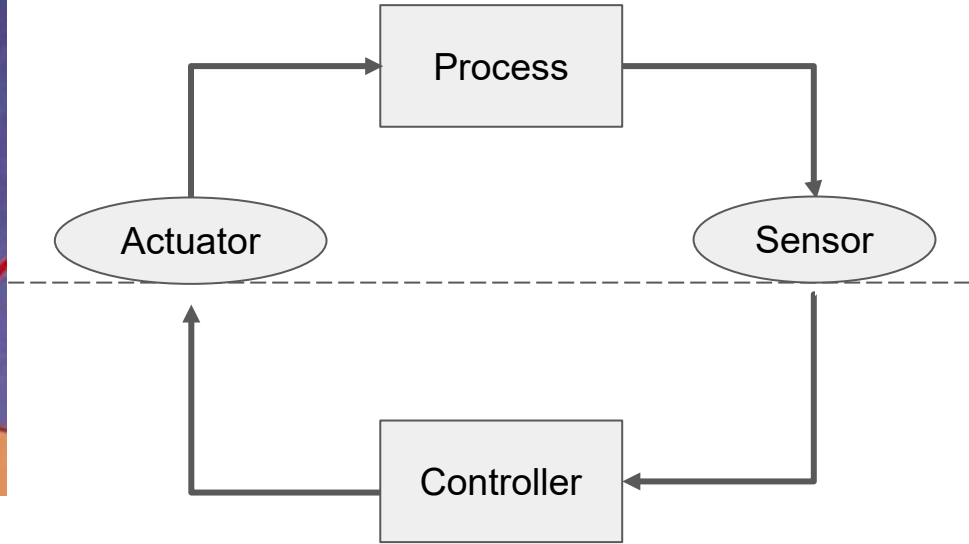
- Feedback
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- Observable
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- Event-driven





CPS Properties

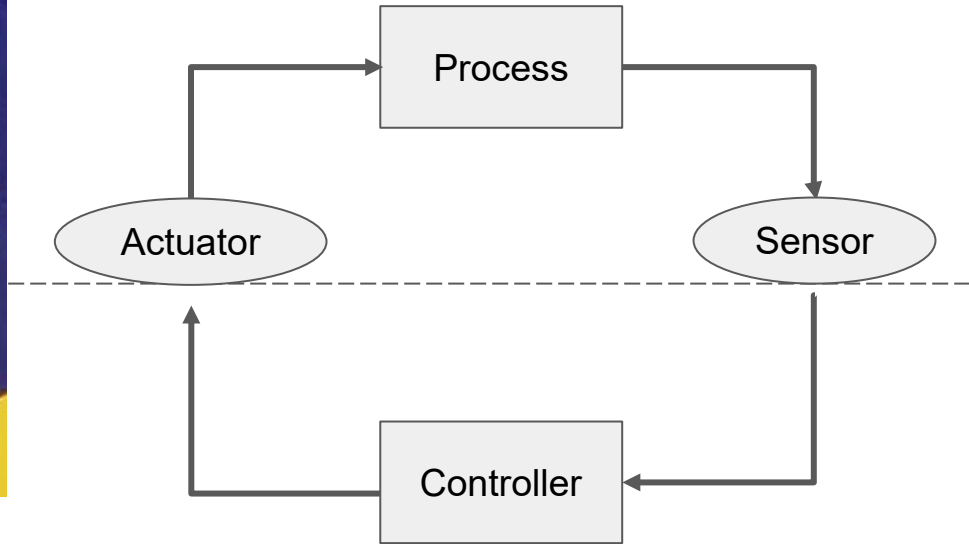
- Feedback
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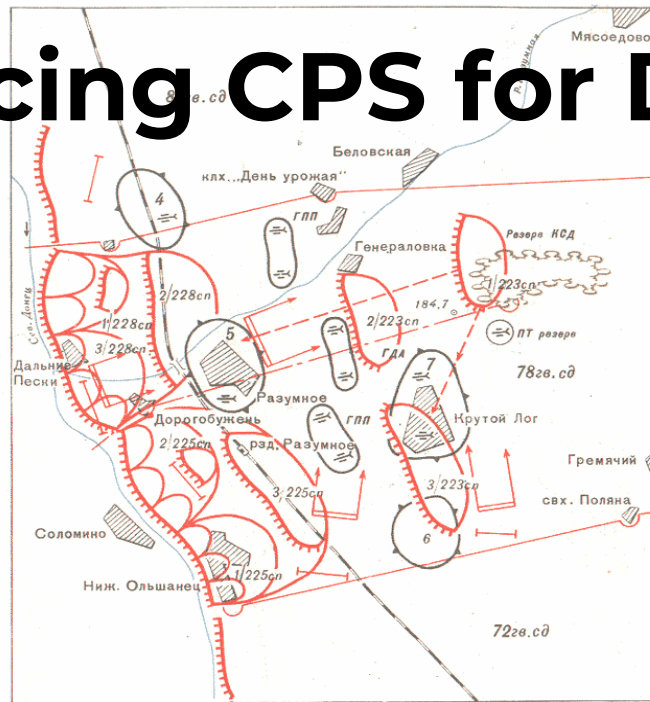


CPS Properties

- Feedback
- Dynamic
- Observable
- Physically Bounded
- Error Tolerant
- Event-driven



Embracing CPS for Defense





Defenses

Prevention





Defenses

Prevention

Detection





Defenses

Prevention



Detection



Mitigation





Prevention

Authentication



Prevention: Authentication

How to ensure that sensors are genuinely reporting valid information?



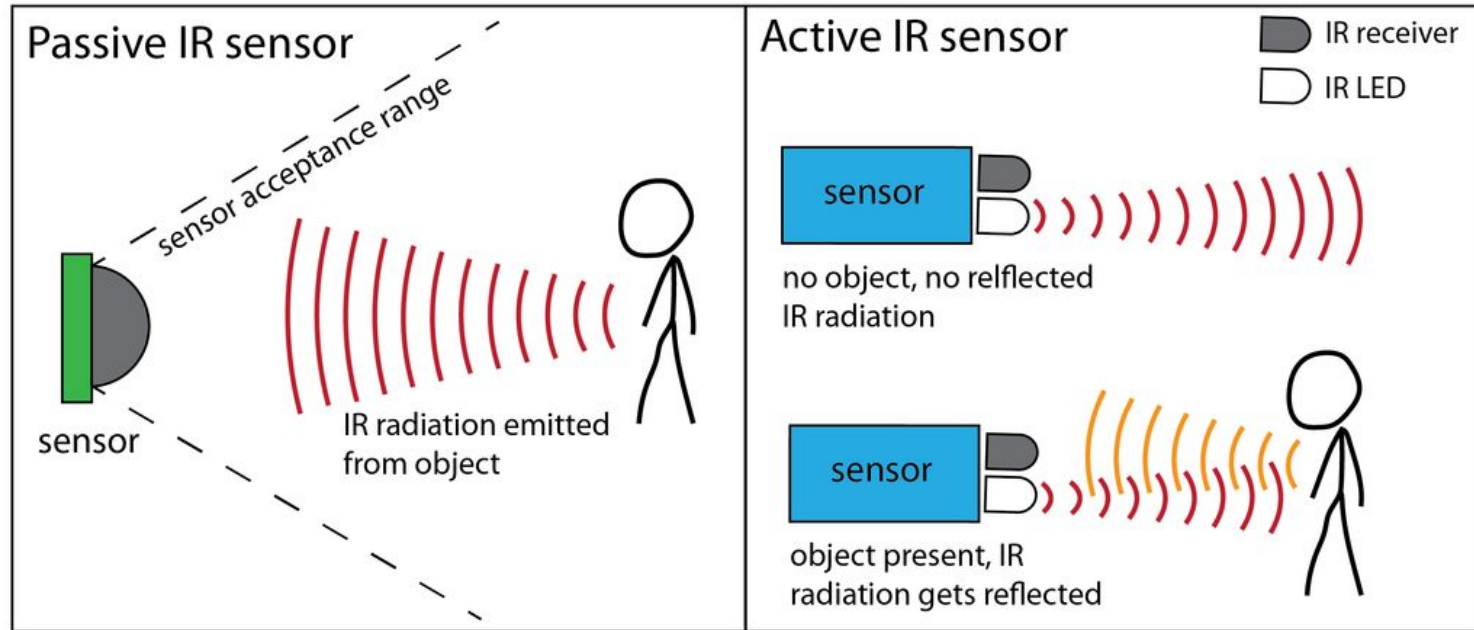
Prevention: Authentication

Shoukry et al. [11]

PyCRA: Physical Challenge-Response Authentication For
Active Sensors Under Spoofing Attacks



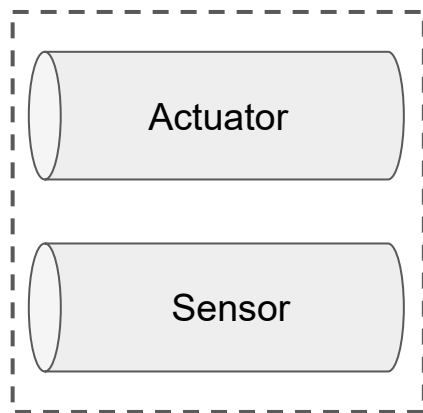
Prevention: Authentication





Prevention: Authentication

Active Sensor

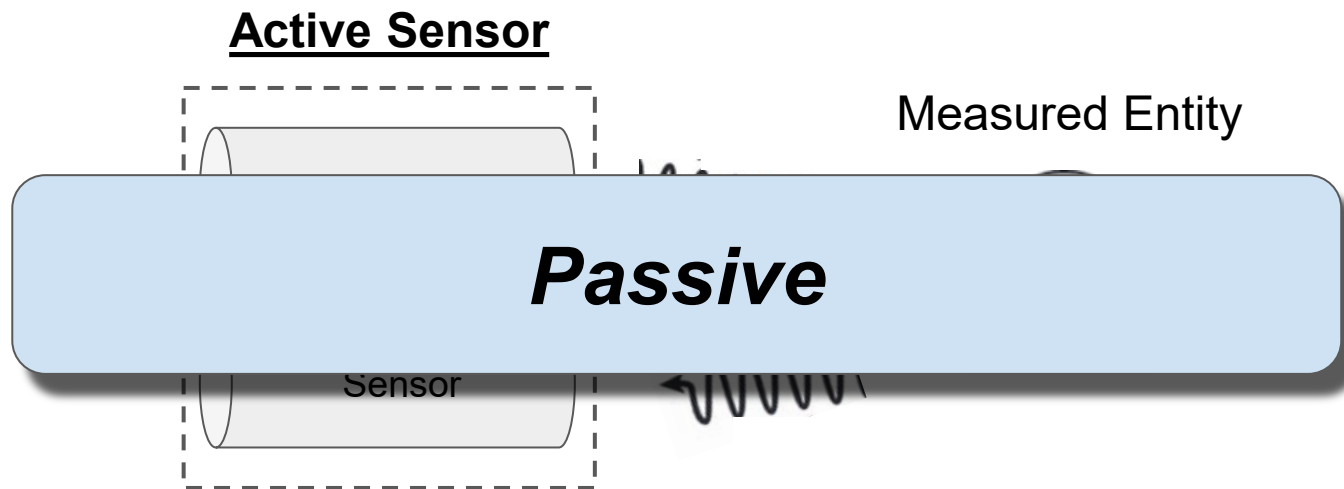


Measured Entity





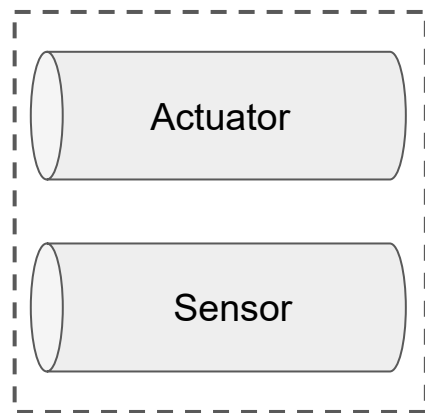
Prevention: Authentication



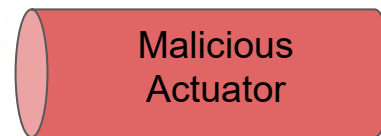


Prevention: Authentication

Active Sensor

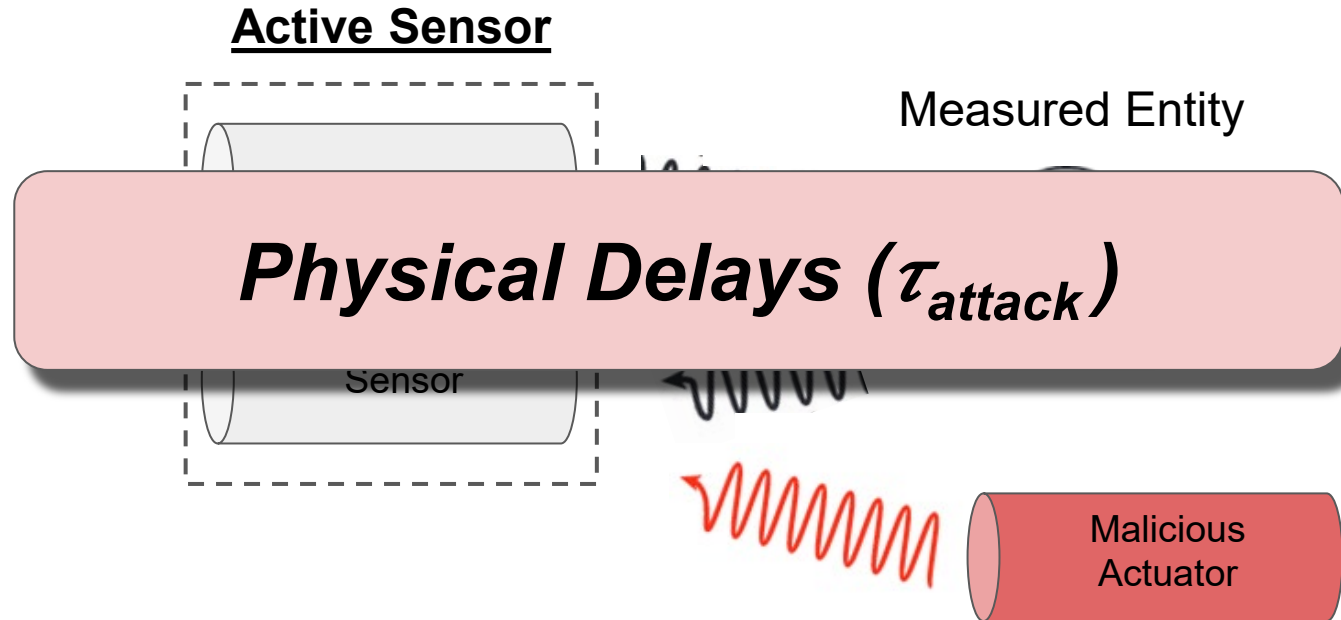


Measured Entity



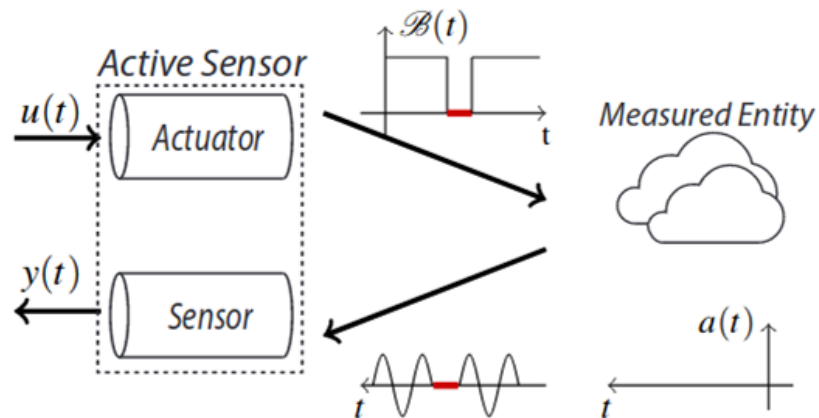


Prevention: Authentication





Prevention: Authentication

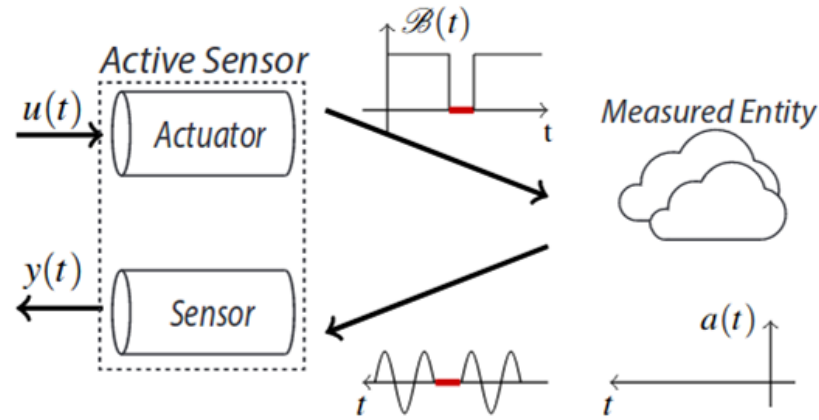


(b)

Operation with PyCRA



Prevention: Authentication

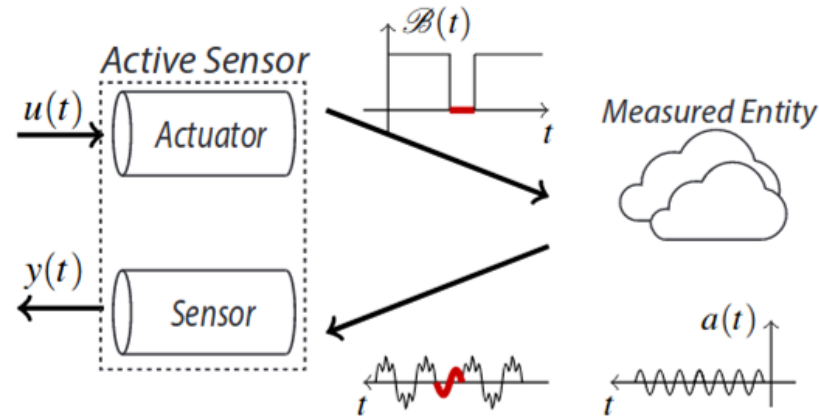


(b)

$$B(t) = u(t)A(t), \quad u(t) \in \{0, 1\}$$



Prevention: Authentication



(c)

**Under Attack with
PyCRA**



Prevention: Authentication

Take Away

Fundamental properties of sensor physics
can be useful for defense.



Prevention

- **Formal Methods**

- Mitra et al. [12] - Verifying Cyber-Physical Interactions in Safety-Critical Systems
- Bohrer et al. [13] - VeriPhy: Verified Controller Executables from Verified Cyber-Physical System Models

- **Memory Safety**

- Clements et al. [14] - Protecting Bare-Metal Embedded Systems with Privilege Overlays

- **Resilient Control**

- Ivanov et al. [15] - Attack-resilient Sensor Fusion for Safety Critical Cyber-Physical Systems

- **System Architecture**

- Liu et al. [16] - Secure Autonomous Cyber-Physical Systems Through Verifiable Information Control Flow



Detection

Intrusion Detection



Detection

How to detect if a system is behaving maliciously?



Detection: IDS

Cheng et al. [21]

Orpheus: Enforcing Cyber-Physical Execution Semantics to
Defend Against Data-Oriented Attacks



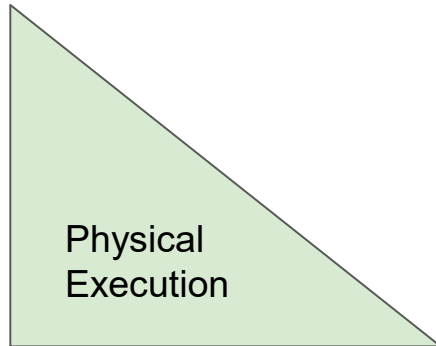
Detection: IDS

How to detect if **software** is behaving maliciously?



Detection: IDS

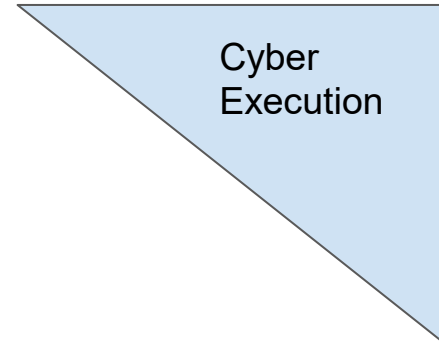
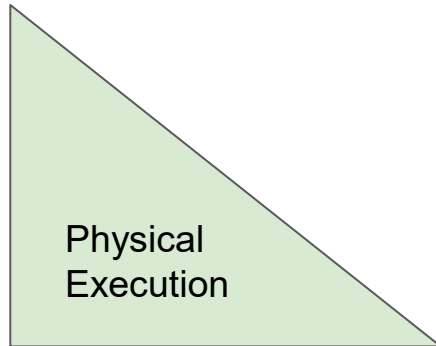
How to detect if **software** is behaving maliciously?





Detection: IDS

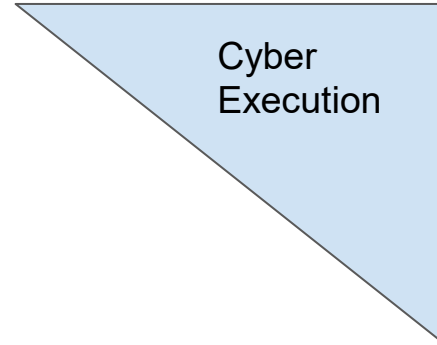
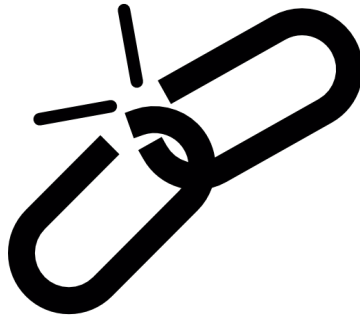
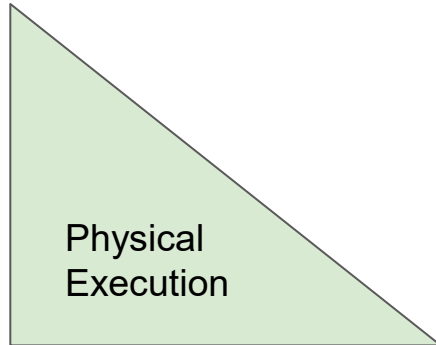
How to detect if **software** is behaving maliciously?





Detection: IDS

How to detect if **software** is behaving maliciously?





Detection: IDS

```
① while (...) {  
②     eventRead();  
③ ✖ if (Push_Event())  
④     push-syringe();  
⑤ ✖ else if (Pull_Event())  
⑥     pull-syringe();  
⑦     ...  
⑧ }
```

(a)

Attacks on control branch
Execute a *valid-yet-unexpected* control flow path (eg. dispensing drugs at an unscheduled time).

```
⑨ push-syringe() {  
⑩ ✖ steps = ... ;  
⑪     for (i=0; i<steps; i++)  
⑫     {  
⑬         write(i2c, ...);  
⑭         ...  
⑮     }  
⑯ }
```

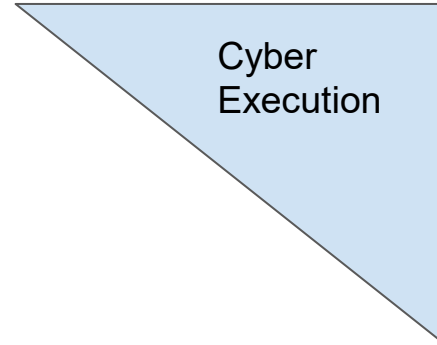
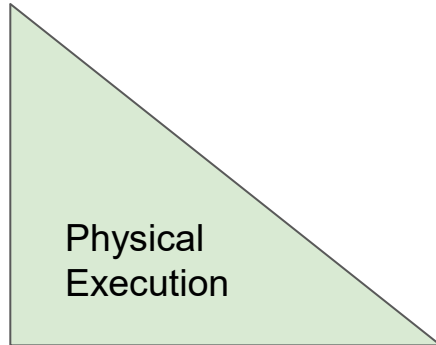
(b)

Attacks on control intensity
Manipulate the amount of control operations (eg. dispensing too much of a drug).



Detection: IDS

How to detect if **software** is behaving maliciously?





Detection: IDS

How to detect if **software** is behaving maliciously?



Cyber-Physical
Execution

A large cyan square box with a thin black border, centered on the slide. Inside the box, the text "Cyber-Physical Execution" is written in black, centered.



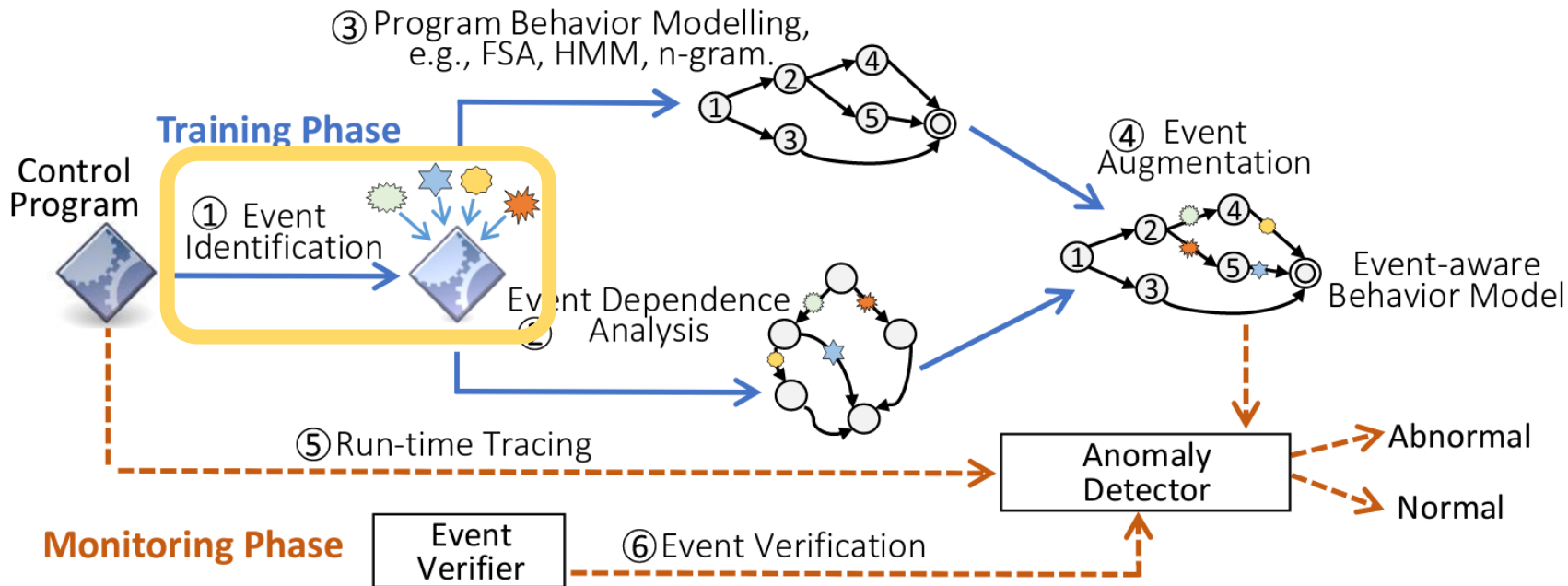
Detection: IDS

How to detect if software is behaving maliciously?

Augment **physical event constraints** on top of a program behavior model.

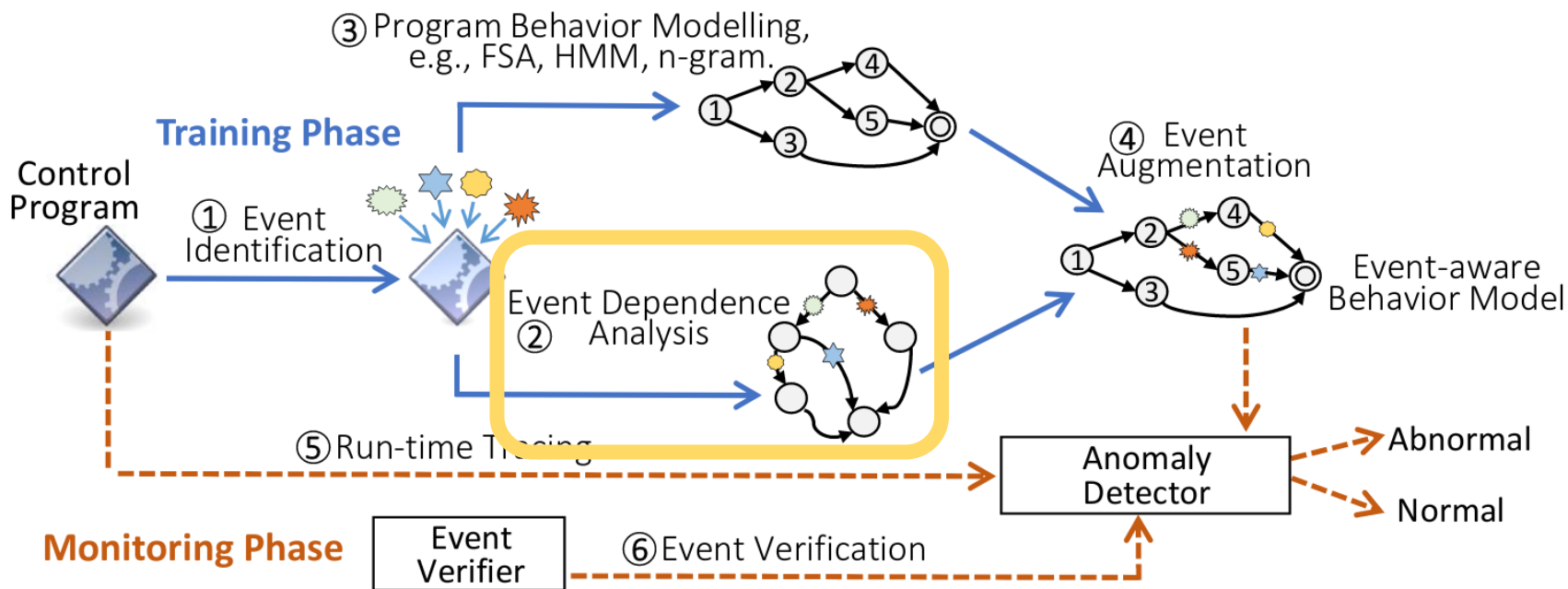


Detection: IDS



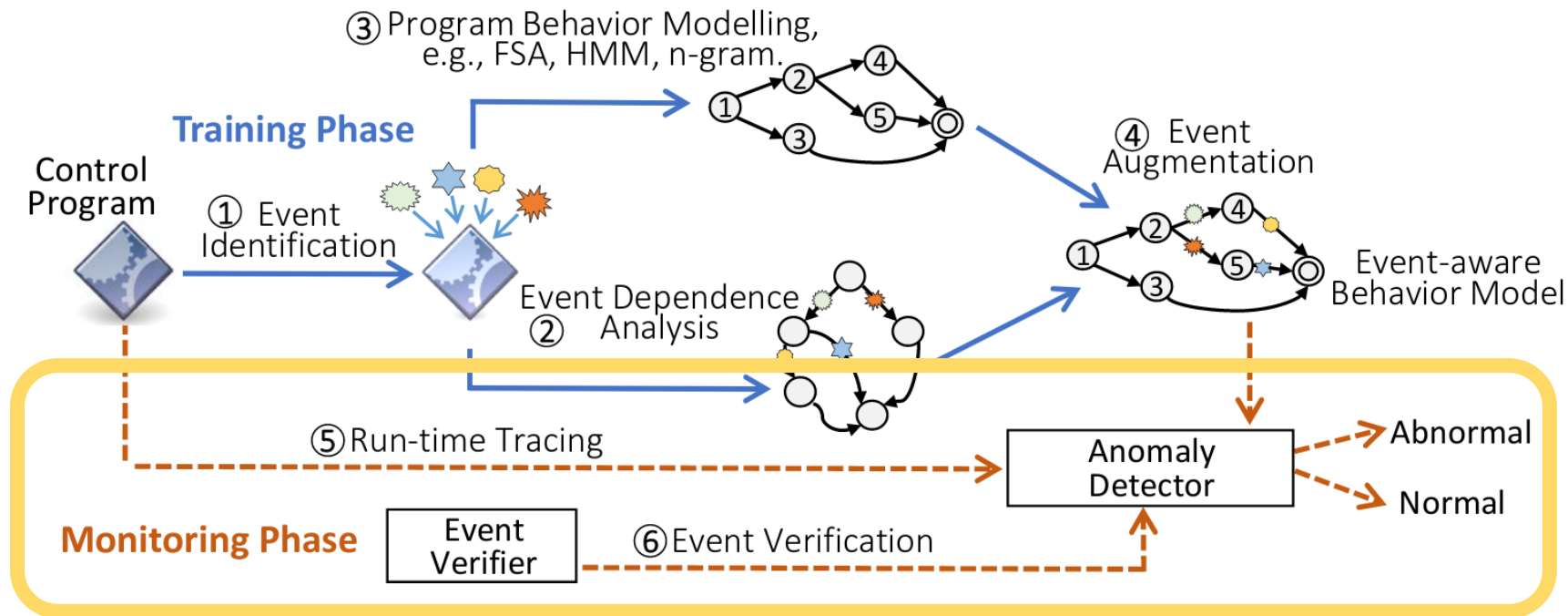


Detection: IDS





Detection: IDS





Detection: IDS

Take Away

Fusion of program & physical event contexts
can strengthen software.



Detection

- Attestation

- Valente and Cardenas [17] - Using Visual Challenges to Verify the Integrity of Security Cameras
- Chen et al. [18] - Learning From Mutants: Using Code Mutation to Learn and Monitor Invariants of a Cyber-Physical System

- Vulnerability Discovery

- Corteggiani et al. [22] - Inception: System-wide Security Testing of Real-world Embedded Systems Software
- Pustogarov et al. [23] - Using Program Analysis to Synthesize Sensor Spoofing Attacks



Mitigation

Reconfiguration



Mitigation: Reconfiguration

How to make systems that can survive attacks?



Mitigation: Reconfiguration

Abdi et al. [24]

Guaranteed Physical Security with Restart-Based Design
for Cyber-Physical Systems

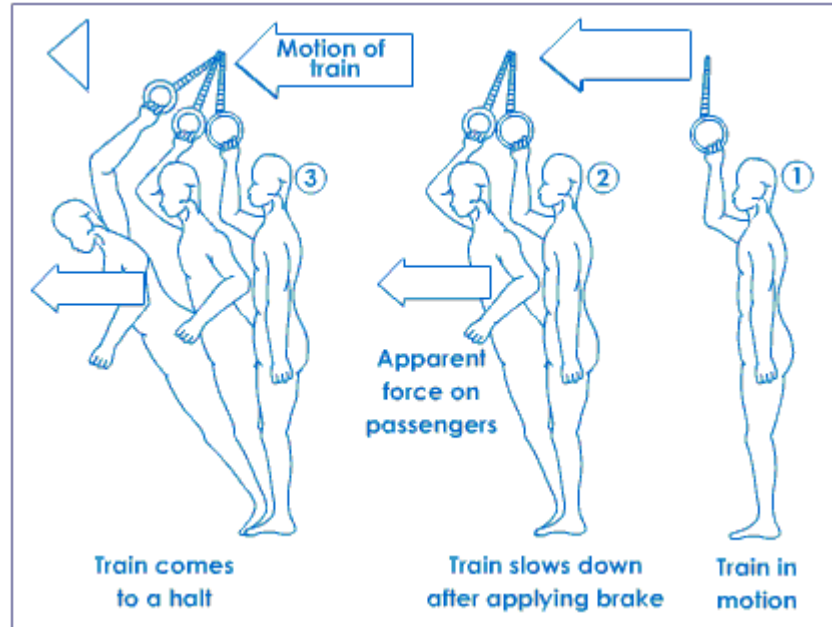


Mitigation: Reconfiguration





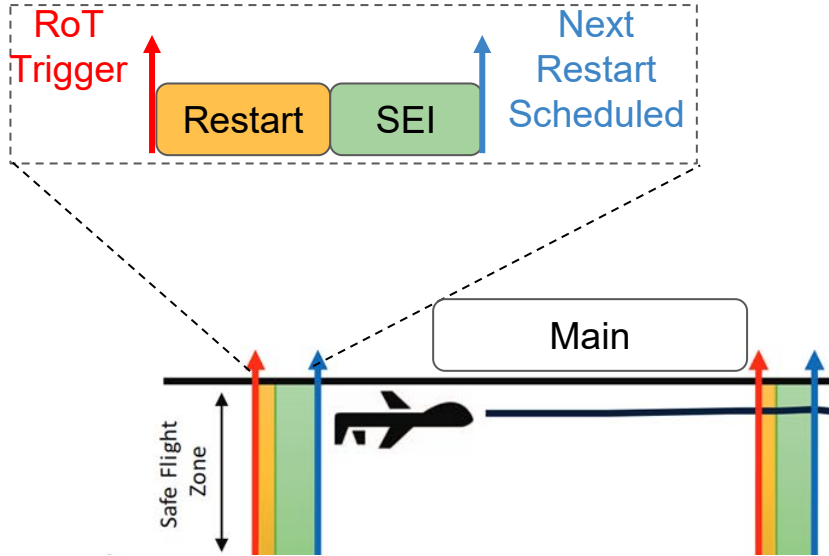
Mitigation: Reconfiguration



Inertia

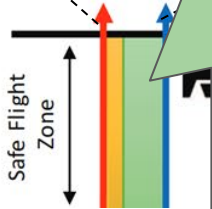
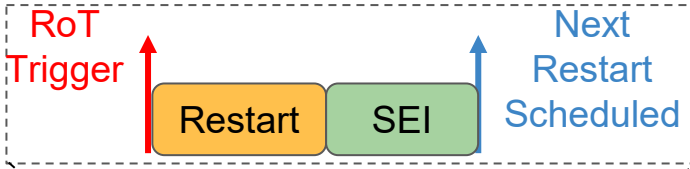


Mitigation: Reconfiguration





Mitigation: Reconfiguration

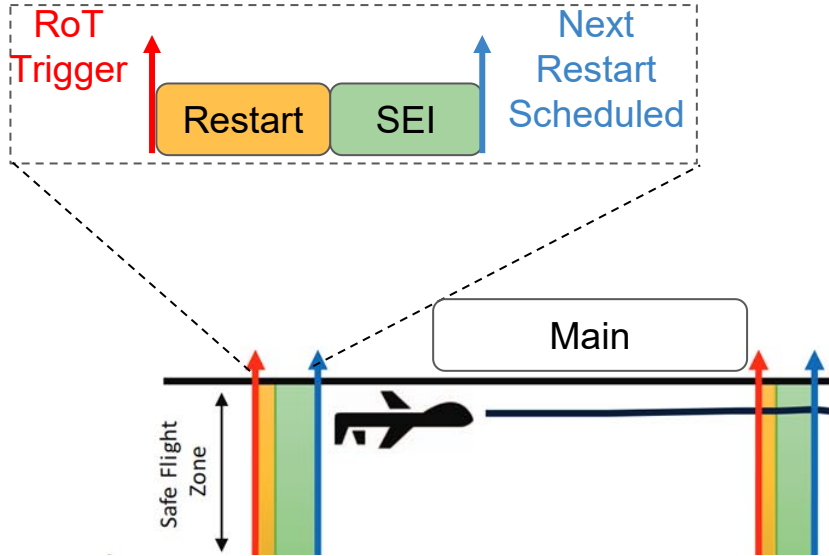


Secure Execution Interval

- FindRestartTime
 - Calculates restart times s.t the physical plant *cannot* reach an unsafe state until the restart takes place and, at the beginning of the next SEI, the state is still *recoverable* by the Safety Controller.
- SafetyController
 - Stabilizes the system if needed.

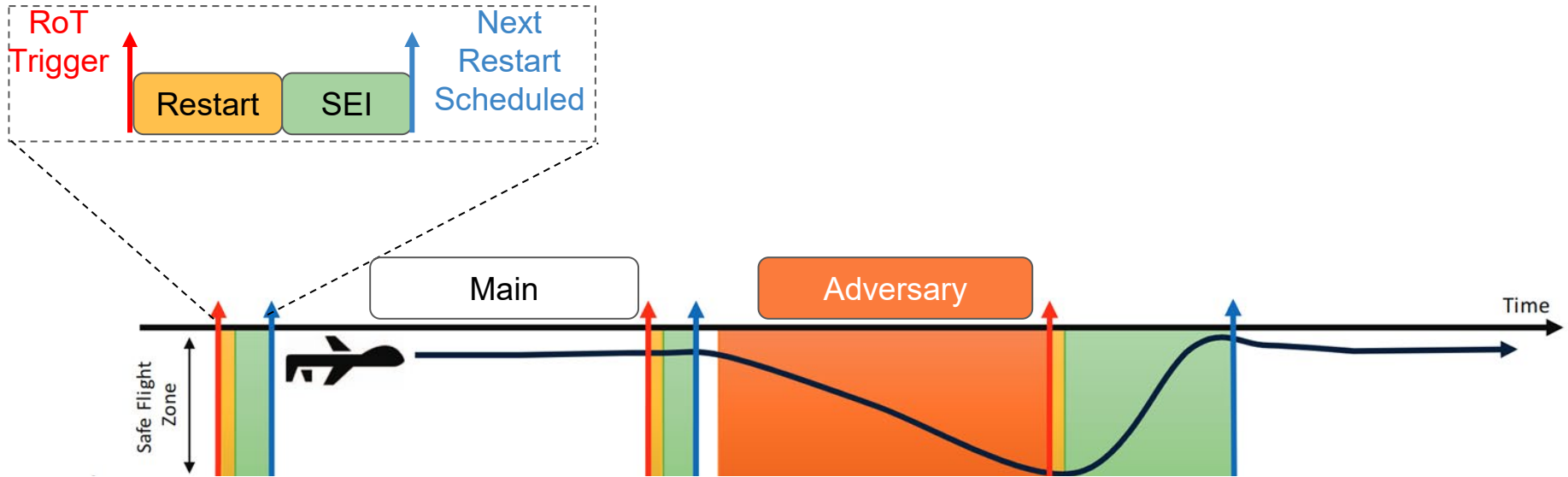


Mitigation: Reconfiguration





Mitigation: Reconfiguration





Mitigation: Reconfiguration

Take Away

Inertia can help build attack-tolerant systems.



Defenses

Common Theme





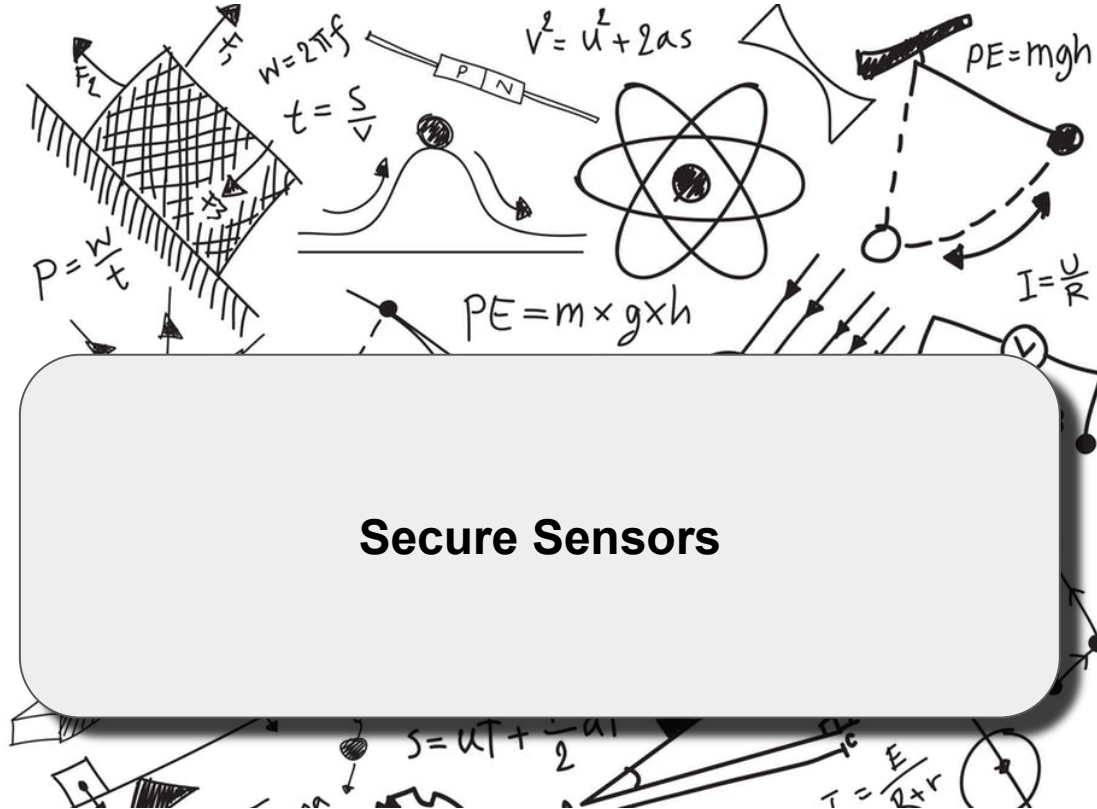
Defenses

Physics

$w = 2\pi r f$
 $t = \frac{s}{v}$
 $v^2 = u^2 + 2as$
 $PE = mgh$
 $I = \frac{U}{R}$
 $PE = m \times g \times h$
 $S = vt$
 $S = \left(\frac{u+v}{2}\right)t$
 $E = mg^2$
 $s = ut + \frac{1}{2}at^2$
 $\tau = \frac{E}{R+r}$
 $P = \frac{W}{t}$
 $PE = mgh$ (pendulum)
 $I = \frac{U}{R}$ (circuit with voltmeter and ammeter)
 $E = mg^2$ (magnet)
 $s = ut + \frac{1}{2}at^2$ (inclined plane)
 $\tau = \frac{E}{R+r}$ (circuit with battery and resistor)



Defenses



Secure Sensors



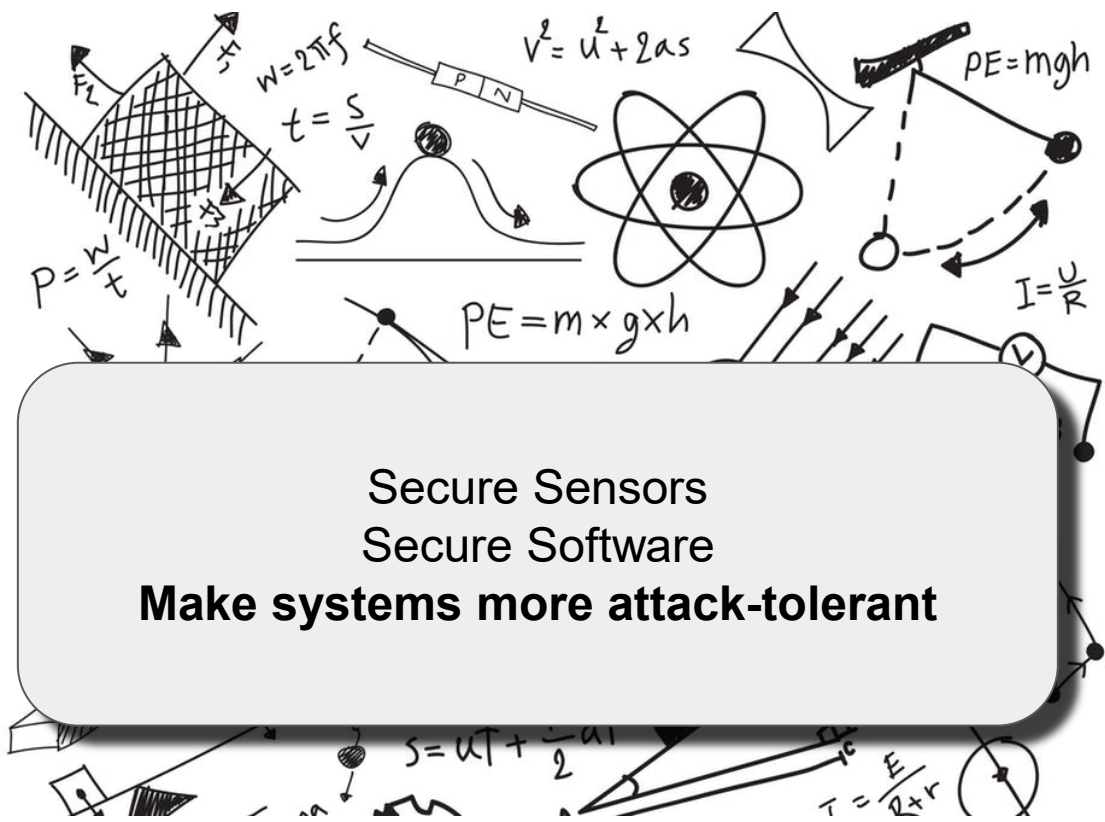
Defenses



Secure Sensors
Secure Software



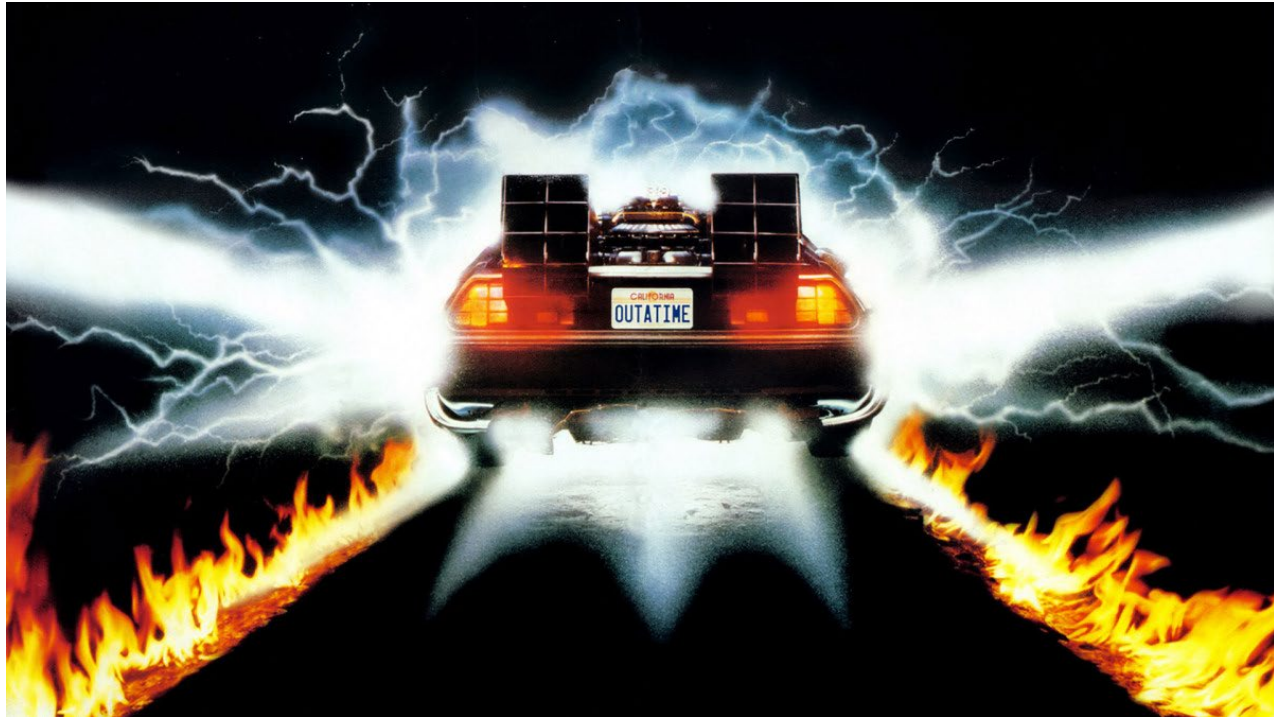
Defenses



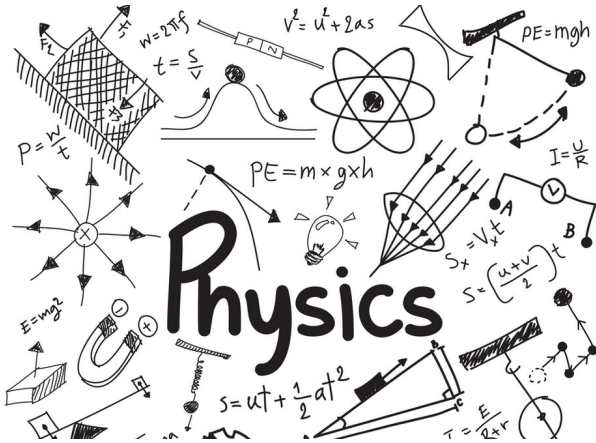
Secure Sensors
Secure Software
Make systems more attack-tolerant



Future Work



Future Work



- Tailored Defenses for CPS.



- Distributed CPS

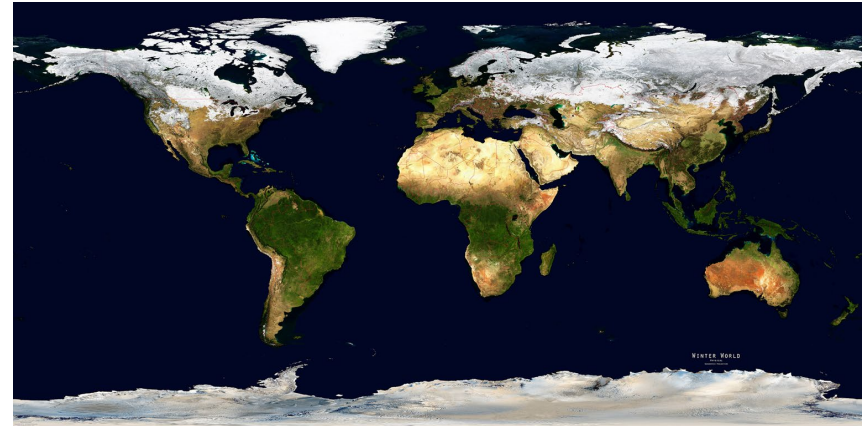
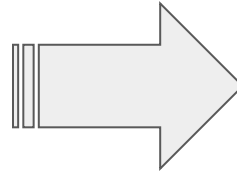


In Summary

CPS Security is Different



Today



Tomorrow



In Summary

CPS Security is Different



Questions?

